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SOURCE-CODE

FOR SAMPLE WORKS

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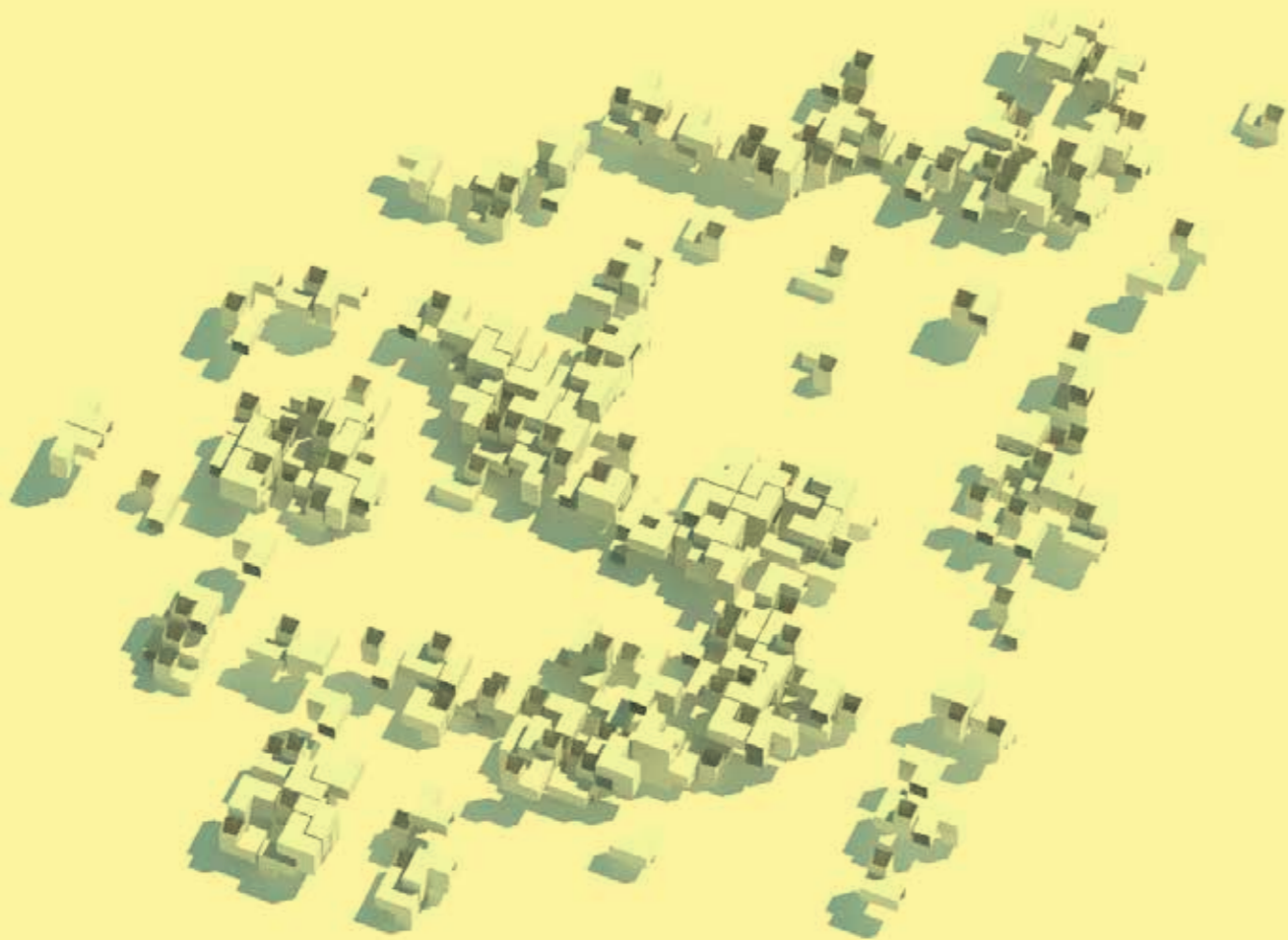
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SOURCE CODE FOR PROTOCELL GENERATIVE HOUSING SYSTEM. THE ALGORITHM, INITIALLY IMPLEMENTED IN RHINOSCRIPT, CAN BE DIVIDED INTO THREE ISOLATED STAGES. THE FIRST DISTRIBUTES CELLULAR MASS ACCORDING A CA LOGIC AND OPTIMIZER THAT ADJUSTS MASSING FOR CIRCULATION PATHS AND OTHER ENCODED CONSTRAINTS LIKE SITE, TOPOGRAPHIC FEATURES, ETC. THE FIRST STAGE REQUIRES AS INPUT AN INITIAL MASSING CONDITION AS CELLULAR AUTOMATA PROCEEDS AS INCREMENTAL REFINEMENT.[1] FIRST STAGE IS ALSO RESPONSIBLE FOR CONSTRUCTING A CELL NETWORK, IE. EACH CELL MAINTAINS STATE AND KEEPS TRACK OF NEIGHBORING CELLS. THIS NETWORK IS PASSED TO STAGE TWO ALONG WITH FURTHER BUILDING CONSTRAINTS LIKE PROGRAM, FLOORSPACE ALLOCATION, ETC. THE SECOND STAGE SUBDIVIDES SINGLE-CELL MASS INTO MULTI-CELL CLUSTERS OR LINKED CELL CHAINS. THIS IS ACCOMPLISHED BY ESTABLISHING AN INITIAL CONDITION OF RANDOMLY PLACED CONDITIONAL UNITS AND DEFINING A FITNESS FUNCTION THAT EVALUATES THE PLACEMENT AND SITUATION OF THE UNIT AND SIMPLY DISCARDS LOSERS AND IGNORES WINNERS. THIS IS A WEAK GENETIC OPTIMIZATION ALGORITHM THAT IS MORE BRUTE FORCE THAN ANYTHING ELSE, BUT IT DOES FIND SOLUTIONS IN REASONABLE AMOUNT OF TIME. THE FINAL STAGE EMBEDS BUILDING INTELLIGENCE INTO CELL CLUSTERS, PLACES UTILITY CORE, AND ADAPTS UNIT TO BASIC BUILDING CONSTRAINTS... ALL STAGES ARE INTENDED TO BE A GUIDED META-DESIGN PROCESSES, IN WHICH DESIGNERS PARTICIPATE IN REAL TIME BY MAKING SUBJECTIVE DECISIONS AND FEEDING THEM BACK INTO THE SYSTEM.



```
-----
'Smart cells v1
'
'
-----
Option Explicit
'Script written by Josh Parker
'Script copyrighted by OPEN Architecture
'Script version Tuesday, February 15, 2011 3:25:36 AM

Call Main()
Sub Main()

    Dim arrPts, intSteps, intLevels, intSpacing, oMajRule
    Dim oSubstr, oSnakeFarm

    'get initial data
    arrPts=Rhino.GetObjects("select points to populate",1)
    If Not IsArray(arrPts) Then
        Rhino.Print "no points selected"
        Exit Sub
    End If
    intSpacing=Rhino.GetInteger("enter cell spacing",5)
    intSteps=Rhino.GetInteger("enter number of steps",2)
    intLevels=Rhino.GetInteger("enter number of levels",2)

    'create substrate
    Set oSubstr = New Substrate
    'substrate "constructor"
    Call oSubstr.Build(intSpacing, intSteps, intLevels)
    'add cells from points
    Call oSubstr.AddCellsByColor(arrPts)
    'link each cell to its neighbors
    Call oSubstr.ConnectCells()
    'group cells by type
    Call oSubstr.GroupCells()
    'color cell pts by cell type
    Call oSubstr.ColorByType()

    'create snakes
    Set oSnakeFarm = New SnakeFarm
    'locate snakes in substrate
    Call oSnakeFarm.FindSnakes(oSubstr, 4)
    'spine the snakes
    Call oSnakeFarm.SpineSnakes()
    'skin the snakes
    Call oSnakeFarm.SkinSnakes((CDBl(intSpacing)/2)*.9)

    'create massing
    'Set oMass = New massing
    'build mass from snake formation
    'oMass.build(oSnakes)

End Sub

'-----
'Cell CLASS
'
'
'-----
Option Explicit
'Script written by Josh Parker
'Script copyrighted by OPEN Architecture
'Script version Tuesday, February 15, 2011 3:25:36 AM

Class Cell

    Public m_intType
    Public m_strPt

    'array of neighbors
    Public m_arrNeighbors
    Public m_arrVonNeumanns

    'moore subsets
    Public m_arrType0Ms
    Public m_arrType1Ms
    Public m_arrType2Ms

    'vonneumann subsets
    Public m_arrType0VNs
    Public m_arrType1VNs

Public m_arrType2VNs

'neighbor pointers
Public m_objNorth
Public m_objSouth
Public m_objEast
Public m_objWest
Public m_objTop
Public m_objBottom

'is cell part of snake
Public m_boolIsOpen

Private Sub Class_Initialize
    Rhino.Print "Initialize cell"
    m_boolIsOpen = True
End Sub

Private Sub Class_Terminate
    Rhino.Print "Terminate cell"
End Sub

Public Sub Build(strPt, intType)

    m_intType = intType
    m_strPt = strPt

End Sub

Public Sub Connect(arrCells, intRadius)

    'check arg is valid non-empty array
    If IsEmpty(arrCells) Or IsNull(arrCells) Then
        Rhino.Print "Connect arg, arrCells is empty or
null"
        Exit Sub
    ElseIf Not IsArray(arrCells) Then
        Rhino.Print "Connect arg, arrCells is not an ar-
ray, its a: " + TypeName(arrCells)
        Exit Sub
    End If

    Call FindNeighbors(arrCells, intRadius)
    'Call PointAtNeighbors()
    Call GroupNeighbors()
    Call GroupVonNeumanns()

End Sub

'find neighbors and create ordered array of pointers-----
Private Sub PointAtNeighbors()

    Dim c, p1, p2

    'sort neighbors
    For Each c In m_arrNeighbors

        'get coordinate of target and point
        p1=Rhino.PointCoordinates(m_strPt)
        p2=Rhino.PointCoordinates(c.m_strPt)

        If p2(1) > p1(1) Then
            'y is >, its on north
            Set m_objNorth = c
        ElseIf p2(1) < p1(1) Then
            'y is <, its on south
            Set m_objSouth = c
        ElseIf p2(0) > p1(0) Then
            'x is >, its on east
            Set m_objEast = c
        ElseIf p2(0) < p1(0) Then
            'x is <, its on west
            Set m_objWest = c
        ElseIf p2(2) > p1(2) Then
            'z is >, its on top
            Set m_objTop = c
        ElseIf p2(2) < p1(2) Then
            'z is <, its on bottom
            Set m_objBottom = c
        Else
            Rhino.Print "ignore, same cell"
        End If
    Next

Next
```

```

End Sub

'Get points within radius from cell pt-----
Private Sub FindNeighbors(arrCells, intRadius)

    Dim c, d, i, j, closeCells(), adjacentCells(), p1, p2

    i=0
    j=0
    For Each c In arrCells
        'calc distance to cell c
        p1=Rhino.PointCoordinates(m_strPt)
        p2=Rhino.PointCoordinates(c.m_strPt)
        d=Rhino.Distance(p1,p2)
        'if its within radius, its adjacent
        If d<=(intRadius*1.1) And d>0 Then
            ReDim Preserve adjacentCells(i)
            Set adjacentCells(i) = c
            i=i+1
        End If
        'if its within 1.5radius, its close
        If d<=(intRadius*1.5) And d>0 Then
            ReDim Preserve closeCells(j)
            Set closeCells(j) = c
            j=j+1
        End If
    Next

    'set if any
    If i>0 Then
        m_arrVonNeumanns = adjacentCells
    Else
        Rhino.Print "no von neumanns"
        Rhino.ObjectColor m_strPt, RGB(0, 0, 255)
    End If

    'set if any
    If j>0 Then
        m_arrNeighbors = closeCells
    Else
        Rhino.Print "no moores"
        Rhino.ObjectColor m_strPt, RGB(0, 255, 0)
    End If

End Sub

'Group neighbors by type-----
Public Sub GroupNeighbors()
    'Rhino.Print "Grouping Neighbors"

    Dim type0(), type1(), type2()
    Dim i, a, b, c
    a=0
    b=0
    c=0

    If IsNull(m_arrVonNeumanns) Then Exit Sub

    For i=0 To Ubound(m_arrVonNeumanns)

        'group by type
        Select Case m_arrNeighbors(i).m_intType
            Case 0
                ReDim Preserve type0(a)
                Set type0(a) = m_
                a=a+1
            Case 1
                ReDim Preserve type1(b)
                Set type1(b) = m_
                b=b+1
            Case 2
                ReDim Preserve type2(c)
                Set type2(c) = m_
                c=c+1
            Case Else
                Rhino.Print "GroupVonNeumanns()"
        End Select

        'copy if smth to copy, else leave empty
        If a > 0 Then m_arrType0VNs = type0
        If b > 0 Then m_arrType1VNs = type1
        If c > 0 Then m_arrType2VNs = type2

    Next

End Sub

'color by type-----
Public Sub UpdateColor()

    Dim color

    'set color var by cell type
    Select Case m_intType
        Case 0
            color = RGB(255, 0, 0)
        Case 1
            color = RGB(0, 255, 0)
        Case 2
            color = RGB(0, 0, 255)
        Case Else
            color = RGB(255, 255, 255)
    End Select

    'set object color
    Rhino.ObjectColor m_strPt, color

End Sub

'apply ruleset-----
Public Sub Apply(oRuleSet)

    Dim newType

    'calculate new type
    'newType = oRuleSet.Apply(m_objNorth, m_objSouth, m_objEast, m_objWest, m_objTop, m_objBottom)
    newType = oRuleSet.Apply2(m_arrNeighbors)

    'set new type
    m_intType = newType

End Sub

'-----
Public Sub MajorityRuleStep()

    'count number of a,b,c types within neighbors

End Sub

```

```

'set type to that type
End Sub

End Class

'-----
'MajorityRule CLASS
'
'-----
Option Explicit
'Script written by <insert name>
'Script copyrighted by <insert company name>
'Script version Thursday, February 17, 2011 11:50:25 PM

Class MajorityRule

    Public Function Apply(n,s,e,w,t,b)

        Dim cells, counts, c, i

        cells = Array(n,s,e,w,t,b)
        counts = Array(0,0,0)

        'count number of each type
        For Each c In cells
            Rhino.Print TypeName(c)
            If Not IsEmpty(c) Then
                Select Case c.m_intType
                    Case 0
                        counts(0)=counts(0)+1
                    Case 1
                        counts(1)=counts(1)+1
                    Case 2
                        counts(2)=counts(2)+1
                    Case Else
                        'do nothing
                End Select
            Else
                'is null b/c no cell
                Rhino.Print "skip " + TypeName(c)
            End If
        Next

        'return most numerous type
        For i=0 To Ubound(counts)
            If counts(i) = Max(counts) Then
                Apply = i
            End If
        Next

    End Function

    'This one is better
    Public Function Apply2(arrCells)

        Dim cells, counts, c, i, j, maj(), iRand

        'cells = Array(n,s,e,w,t,b)
        counts = Array(0,0,0)

        'count number of each type
        For Each c In arrCells
            If Not IsEmpty(c) Then
                Select Case c.m_intType
                    Case 0
                        counts(0)=counts(0)+1
                    Case 1
                        counts(1)=counts(1)+1
                    Case 2
                        counts(2)=counts(2)+1
                    Case Else
                        'do nothing
                End Select
            Else
                'is null b/c no cell
                Rhino.Print "skip " + TypeName(c)
            End If
        Next

        'return most numerous type
        j=0
        For i=0 To Ubound(counts)
            If counts(i) = Max(counts) Then

```

```

            ReDim Preserve maj(j)
            maj(j) = i
            j=j+1
        End If
    Next

    'if tie
    If (Ubound(maj)>0) Then
        'get random max
        iRand=RndInt(0,Ubound(maj))
        Apply2 = maj(iRand)
    Else
        Apply2 = maj(0)
    End If

End Function

End Class
Option Explicit
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'Script version Tuesday, February 15, 2011 3:25:36 AM

'-----
'SNAKEFARM CLASS
'
'-----
Class SnakeFarm

    Public m_arrSnakes
    Public m_intSnakeCnt

    Public Sub FindSnakes(oSubstr, intSize)

        Dim snakeCells, newSnakes()
        Dim i, failed, invalid

        'check args
        If IsNull(oSubstr) Then
            Rhino.Print "FindSnakes arg, oSubstr is null"
            Exit Sub
        ElseIf Not TypeName(oSubstr) = "Substrate" Then
            Rhino.Print "FindSnakes arg, oSubstr not a Substrate, its a: " + TypeName(oSubstr)
            Exit Sub
        End If

        i=0
        failed = 0
        invalid = 0

        'find snakes
        Do While failed<500
            'get next set of cells
            snakeCells = NextSnake(oSubstr, intSize)
            'if not invalid or null, make a snake and add to farm
            If IsNull(snakeCells) Then
                'found a short snake, increment failed
                failed=failed+1
                Rhino.Print "found short snake, short count: " + CStr(failed)
            Else
                Rhino.Print "found snake, size: " + CStr(Ubound(snakeCells)+1)
                ReDim Preserve newSnakes(i)
                'create new snake
                Set newSnakes(i) = New Snake
                'build snake
                Call newSnakes(i).build(snakeCells)
                i=i+1
            End If
        Loop

        If i>0 Then m_arrSnakes = newSnakes

    End Sub

    'find snake-----
    Public Function NextSnake(oSubstr, intSize)

        Dim oRndCell, arrOpenCells, snakeCells(), snakeCells2(), i, n
        Dim arrBB, strBB, arrVol, strSpine

```

```

'check for valid args
If IsNull(oSubstr) Or IsEmpty(oSubstr) Then
    Rhino.Print "NextSnake arg, oSubstr is null or
empty"
    NextSnake = Null
    Exit Function
ElseIf Not IsArray(oSubstr.m_arrType0) Then
    Rhino.Print "NextSnake arg, oSubstr.m_arrType0
is not an array, its a: " + TypeName(oSubstr.m_arrType0)
    NextSnake = Null
    Exit Function
End If

'get open cells
arrOpenCells = OpenCells(oSubstr.m_arrType0)

If IsNull(arrOpenCells) Then
    'found a short snake, break & return null
    Rhino.Print "no more snakes"
    NextSnake = Null
    Exit Function
End If

'get random cell from open cells
Set oRndCell = RndCell(arrOpenCells)

'create snake
ReDim Preserve snakeCells(0)
Set snakeCells(0)=oRndCell
snakeCells(0).m_boolIsOpen = False
i=1
'while snake size is not met
Do While i < intSize
    'if no where for snake to grow, break
    If IsNull(NextCell(snakeCells(i-1))) Then
        'found a short snake
        Rhino.Print "NextSnake call to Next-
Cell() returned null, its just means its a short snake"
        'release cells and return null and exit
        ReleaseCells(snakeCells)
        NextSnake = Null
        Exit Function
    End If

    'get next cell
    Set n = NextCell(snakeCells(i-1))
    'add to tmp array
    ReDim Preserve snakeCells(i)
    Set snakeCells(i) = n
    'close cell
    snakeCells(i).m_boolIsOpen = False
    i=i+1
Loop

'if snake is 2d, reject it, release cells, and return
null
If CellsCoplanar(snakeCells) Then
    Rhino.Print "NextSnake produced 2d snake, re-
ject"

    'release cells and try again
    ReleaseCells(snakeCells)
    'try again recursively
    NextSnake = NextSnake(oSubstr,intSize)
    Exit Function
End If

'return valid snake
NextSnake = snakeCells
End Function

'addSegs-----
Public Sub ReleaseCells(arrCells)

    Dim c

    'check arg is valid non-empty array
    If IsEmpty(arrCells) Or IsNull(arrCells) Then
        Rhino.Print "ReleaseCells arg, arrCells is empty
or null"
        Exit Sub
    ElseIf Not IsArray(arrCells) Then
        Rhino.Print "ReleaseCells arg, arrCells is not
an array, its a: " + TypeName(arrCells)
        Exit Sub
    End If
End Sub

```

```

End If
For Each c In arrCells
    c.m_boolIsOpen = True
Next
End Sub

'addSegs-----
Public Function NextCell(currCell)

    Dim arrOpenCells

    'check args
    If IsNull(currCell) Or IsEmpty(currCell) Then
        Rhino.Print "currCell is null or empty"
        NextCell = Null
        Exit Function
    ElseIf Not TypeName(currCell) = "Cell" Then
        Rhino.Print "currCellis not a Cell, its a: " +
TypeName(currCell)
        NextCell = Null
        Exit Function
    End If

    'check args
    If IsNull(currCell.m_arrType0VNs) Or IsEmpty(currCell.m_
arrType0VNs) Then
        Rhino.Print "currCell.m_arrType0VNs is null or
empty"
        NextCell = Null
        Exit Function
    ElseIf Not IsArray(currCell.m_arrType0VNs) Then
        Rhino.Print "currCell.m_arrType0VNs is not an
array, its a: " + TypeName(currCell.m_arrType0VNs)
        NextCell = Null
        Exit Function
    End If

    'get open von neumanns
    arrOpenCells = OpenCells(currCell.m_arrType0VNs)

    If Not IsNull(arrOpenCells) Then
        'pick one at random
        Set NextCell = RndCell(arrOpenCells)
    Else
        Rhino.Print "NextCell found no open von neu-
manns"
        NextCell = Null
    End If
End Function

'-----
Public Sub SpineSnakes()

    Dim snake, strNewSpine

    For Each snake In m_arrSnakes

        strNewSpine = StrokeCells(snake.m_arrCells)

        If Not IsNull(strNewSpine) Then
            snake.m_strSpine = strNewSpine
        Else
            'smth is wrong
            Rhino.Print "Null Spine, this should
never happen"
            Exit Sub
        End If
    Next
End Sub

'are the cell pts coplanar??
Private Function CellsCoplanar(arrCells)

    Dim i, arr3dPts(), strPt

    For i=0 To Ubound(arrCells)
        'get pts
        ReDim Preserve arr3dPts(i)
        strPt = arrCells(i).m_strPt
        arr3dPts(i)=Rhino.PointCoordinates(strPt)
    Next
End Function

```

```

'return true if pts are coplanar
CellsCoplanar = Rhino.PointsAreCoplanar(arr3dPts, 1)
End Function

'returns polyline from ordered cell array-----
Private Function StrokeCells(arrCells)

    Dim i, arr3dPts(), strPt, strShortSpine, strLongSpine

    For i=0 To Ubound(arrCells)
        'get pts for next snake
        ReDim Preserve arr3dPts(i)
        strPt = arrCells(i).m_strPt
        arr3dPts(i)=Rhino.PointCoordinates(strPt)
        'label joints
        Call Rhino.AddText(CStr(i), arr3dPts(i))
    Next

    'create polyline
    If Not IsEmpty(arr3dPts) Then
        'create spine
        strShortSpine = Rhino.AddPolyline(arr3dPts)
        'extend curve to account for snub ends
        strLongSpine = Rhino.ExtendCurveLength(strShortS
pine, 0, 2, 2.5)

        'assign to snake
        m_arrSnakes(i).m_strSpine = strLongSpine
    Else
        Rhino.Print "arr3dPts is empty"
        StrokeCells = Null
    End If

    'return polyline
    StrokeCells = strLongSpine
End Function

Public Sub SkinSnakes(dblRadius)

    Dim i, strP0, strP1, arrP0, arrP1
    Dim arrNorm, arrPlane, arrPlane2, strCirc, arrBB
    Dim strCrossSect, strSpine, arrSweeps, strSkin

    For i=0 To Ubound(m_arrSnakes)

        'get origin
        'strP0 = m_arrSnakes(i).m_arrCells(0).m_strPt
        'strP1 = m_arrSnakes(i).m_arrCells(1).m_strPt
        'arrP0 = Rhino.PointCoordinates(strP0)
        'arrP1 = Rhino.PointCoordinates(strP1)
        'get normal vector
        'arrNorm = Rhino.VectorCreate (arrP0, arrP1)
        'create unit plane from normal vector
        'arrPlane = Rhino.PlaneFromNormal (arrP0, ar-
rNorm)

        'get spine
        strSpine = m_arrSnakes(i).m_strSpine
        'curve frame
        arrPlane2 = Rhino.CurvePerpFrame(strSpine,
-2.45)

        If Not IsArray(arrPlane2) Then
            Rhino.Print TypeName(arrPlane2)
            Rhino.ObjectColor m_strSpine, RGB(0,
255, 0)
        End If

        'add circle
        strCirc = Rhino.AddCircle (arrPlane2, dblRadius)
        'get bounding box of circle
        arrBB = Rhino.BoundingBox(strCirc, arrPlane2)
        'create crosssection curv
        strCrossSect = Rhino.AddPolyline(arrBB)
        'sweep spine
        arrSweeps = Rhino.AddSweep1(strSpine, strCross-
Sect)

        'get skin guid
        'Rhino.Print "arrSweeps type: " +
TypeName(arrSweeps(0))
        'strSkin = arrSweeps(0)
        'assine skin to snake
        m_arrSnakes(i).m_strSkin = strSkin
    Next
End Sub

```

```

End Sub
End Class

'-----
'SNAKE CLASS
'-----
Class Snake
    Public m_strSpine
    Public m_strSkin
    Public m_arrCells
    Public m_intSegs

    Public Sub Build(arrCells)

        Dim i

        m_arrCells = arrCells
        m_intSegs = Ubound(arrCells)+1

        For i=0 To Ubound(arrCells)
            arrCells(i).m_boolIsOpen = False
        Next
    End Sub
End Class

'-----
'[SNAKE]SKIN CLASS
'-----
Class Skin
    Private arrScales

End Class

'-----
'[SNAKE]SPINE CLASS
'-----
Class Spine
    'order array of pts
    Private arrCells

    'render snake method
End Class

'-----
'[SNAKE]SCALE CLASS
'-----
Class Scale
    Private strType
    Private oSrf
    'maybe pointers to neighbors (ids)
    'or shit maybe just reference the obj
End Class

Option Explicit
'Script written by Josh Parker
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'Script version Tuesday, February 15, 2011 3:25:36 AM

Class Substrate
    Public m_arrCells
    Public m_intSpacing
    Public m_intSteps
    Public m_intLevels

    'subsets
    Public m_arrType0
    Public m_arrType1
End Class

```

```

Public m_arrType2
Private Sub Class_Initialize
    'Rhino.Print "Initialize substrate"
End Sub
Private Sub Class_Terminate
    'Rhino.Print "Terminate substrate"
End Sub
'seed substrate-----
Public Sub Build(intSpacing, intSteps, intLevels)
    m_intSpacing = intSpacing
    m_intSteps = intSteps
    m_intLevels = intLevels
End Sub
'create random-type cell array from points-----
Public Sub AddCells(arrPts)
    Rhino.Print "Adding Cells"
    Dim newCells(), i
    If IsNull(arrPts) Then
        Rhino.Print "AddCells arg, arrPts, is null"
        Exit Sub
    End If
    For i=0 To Ubound(arrPts)
        'incr cell array by 1
        ReDim Preserve newCells(i)
        'create new cell i
        Set newCells(i) = New Cell
        'cell "constructor"
        newCells(i).Build arrPts(i), RndInt(0,2)
    Next
    'copy array
    m_arrCells = newCells
End Sub
'create random-type cell array from points-----
Public Sub AddCellsByColor(arrPts)
    Rhino.Print "Adding Cells By color"
    Dim newCells(), i, intType
    If IsNull(arrPts) Then
        Rhino.Print "AddCells arg, arrPts, is null"
        Exit Sub
    End If
    For i=0 To Ubound(arrPts)
        'incr cell array by 1
        ReDim Preserve newCells(i)
        'create new cell i
        Set newCells(i) = New Cell
        'cell "constructor"
        Call newCells(i).Build(arrPts(i),
TypeFromColor(arrPts(i)))
    Next
    'copy array
    m_arrCells = newCells
End Sub
'connect to neighbors-----
Public Sub ConnectCells()
    Rhino.Print "Connecting Cells"
    Dim i
    For i=0 To Ubound(m_arrCells)
        Rhino.Print "Connecting Cells " + CStr(i) + " of
" + CStr(Ubound(m_arrCells))
        'connect cell to its neighbors
        m_arrCells(i).Connect m_arrCells, 5
    Next
End Sub
'Group cells by type-----
Public Sub GroupCells()
    Rhino.Print "Grouping Cells"
    Dim type0(), type1(), type2()
    Dim i, a, b, c
    a=0
    b=0
    c=0
    'Rhino.Print "m_arrCells Type: " + TypeName(m_arrCells)
    'Rhino.Print "m_arrCells Size: " + CStr(Ubound(m_ar-
rCells))
    For i=0 To Ubound(m_arrCells)
        'group by type
        'Rhino.Print "Select Type: " + CStr(m_
arrCells(i).m_intType)
        Select Case m_arrCells(i).m_intType
            Case 0
                ReDim Preserve type0(a)
                Set type0(a) = m_arrCells(i)
                a=a+1
            Case 1
                ReDim Preserve type1(b)
                Set type1(b) = m_arrCells(i)
                b=b+1
            Case 2
                ReDim Preserve type2(c)
                Set type2(c) = m_arrCells(i)
                c=c+1
            Case Else
                Rhino.Print "GroupCells() found
bad cell"
        End Select
    Next
    'copy if smth to copy, else leave null
    If a > 0 Then m_arrType0 = type0
    If b > 0 Then m_arrType1 = type1
    If c > 0 Then m_arrType2 = type2
    'Rhino.Print "m_arrType0: " + CStr(Ubound(m_arrType0))
    'Rhino.Print "m_arrType1: " + CStr(Ubound(m_arrType1))
    'Rhino.Print "m_arrType2: " + CStr(Ubound(m_arrType2))
End Sub
'color substrate by type-----
Public Sub ColorByType()
    Rhino.Print "Coloring Cells"
    Dim i, color
    For i=0 To Ubound(m_arrCells)
        'color pt by type
        Call m_arrCells(i).UpdateColor()
    Next
End Sub
'-----
Public Sub Apply(oRuleSet, intSteps)
    Rhino.Print "Applying ruleset"
    Dim i, j, iRand
    For j=0 To intSteps
        'this should be replaced by random cell picker
        For i=0 To Ubound(m_arrCells)
            'get point(string id) at random
            iRand=RndInt(0,Ubound(m_arrCells))
            'color pt by type
            Call m_arrCells(iRand).
UpdateColor()
        Next
    Next
End Sub
'-----
'-----SCRAP-----
'-----
'return reference to random cell
Public Function RndCellold(intType)
    RndCellold = m_arrCells(RndInt(0, Ubound(m_arrCells)))
End Function

```

```

End Function
'return reference to random cell
Public Function RndType0old()
    RndType0old = m_arrType0(RndInt(0, Ubound(m_arrType0)))
End Function
'return reference to random open type0 cell
'this function will eventually have to timeout
Public Function RndOpenType0old()
    Dim c
    Set c = m_arrType0(RndInt(0, Ubound(m_arrType0)))
    If c.m_boolIsOpen Then
        'return c
        RndOpenType0old = c
    Else
        'not found try again
        RndOpenType0old = RndOpenType0()
    End If
End Function
End Class
Option Explicit
'Script written by Josh Parker
'Script copyrighted by OPEN Architecture
'Script version Tuesday, February 15, 2011 3:25:36 AM
Call Main()
Sub Main()
    Dim arrPts, intSteps, intLevels, intSpacing, oMajRule
    Dim oSubstr, oSnakeFarm
    'get initial data
    arrPts=Rhino.GetObjects("select points to populate",1)
    If Not IsArray(arrPts) Then
        Rhino.Print "no points selected"
        Exit Sub
    End If
    intSpacing=Rhino.GetInteger("enter cell spacing",5)
    intSteps=Rhino.GetInteger("enter number of steps",2)
    intLevels=Rhino.GetInteger("enter number of levels",2)
    'create substrate
    Set oSubstr = New Substrate
    'substrate "constructor"
    Call oSubstr.Build(intSpacing, intSteps, intLevels)
    'add cells from points
    Call oSubstr.AddCells(arrPts)
    'link each cell to its neighbors
    Call oSubstr.ConnectCells()
    'create cellular automata obj
    Set oMajRule = New MajorityRule
    'apply ruleset to each cell x times
    Call oSubstr.Apply(oMajRule, 1)
    'color cell pts by cell type
    Call oSubstr.ColorByType()
    'create snakes
    Set oSnakeFarm = New SnakeFarm
    'locate snakes in substrate
    Call oSnakeFarm.FindSnakes(oSubstr, 4)
    'render snakes?
    Call oSnakeFarm.RenderSnakes()
    'create massing
    'Set oMass = New massing
    'build mass from snake formation
    'oMass.build(oSnakes)
End Sub
Option Explicit
'Script written by <insert name>
'Script copyrighted by <insert company name>
'Script version Wednesday, February 16, 2011 8:20:37 PM
Function RndInt(lowest, highest)
    Randomize
    'RndInt=Int((highest - lowest) * Rnd + lowest)
    RndInt=Int((highest - lowest + 1) * Rnd + lowest)
End Function
'return reference to random open type0 cell
'this function will eventually have to time-
out-----
Function OpenCells(arrCells)
    Dim i, j, arrOpenCells()
    'check arg is valid non-empty array
    If IsNull(arrCells) Then
        Rhino.Print "OpenCells arg is null"
        OpenCells = Null
        Exit Function
    ElseIf Not IsArray(arrCells) Then
        Rhino.Print "OpenCells arg is not an array, its a: " +
TypeName(arrCells)
        OpenCells = Null
        Exit Function
    End If
    j=0
    For i=0 To Ubound(arrCells)
        'if open, add to array
        If arrCells(i).m_boolIsOpen Then
            ReDim Preserve arrOpenCells(j)
            Set arrOpenCells(j) = arrCells(i)
            j=j+1
        End If
    Next
    'return subsets if any open, else null
    If j>0 Then
        'Rhino.Print "OpenCells found some open cells in array"
        OpenCells = arrOpenCells
    Else
        Rhino.Print "OpenCells found no open cells in array"
        OpenCells = Null
        Exit Function
    End If
End Function
'return reference to random open type0 cell-----
Function RndCell(arrCells)
    'check arg is valid non-empty array
    If IsNull(arrCells) Then
        Rhino.Print "RndCell arg is null"
        RndCell = Null
        Exit Function
    ElseIf Not IsArray(arrCells) Then
        Rhino.Print "RndCell arg is not an array, its a: " +
TypeName(arrCells)
        RndCell = Null
        Exit Function
    End If
    'arg is non-zero sized array to return random value from it
    Set RndCell = arrCells(RndInt(0, Ubound(arrCells)))
End Function
'return reference to random open type0 cell-----
Function TypeFromColor(strPt)
    Dim c, typ
    c = Rhino.ObjectColor(strPt)
    'set color var by cell type
    Select Case c
        Case RGB(255, 0, 0)
            typ = 0
        Case RGB(0, 255, 0)
            typ = 1
        Case RGB(0, 0, 255)
            typ = 2
        Case Else
            Rhino.Print "pt is not valid color: " + c
            Exit Function
    End Select
End Function

```

```

End Select

'return type
TypeFromColor = typ

End Function

'-----
'-----SCRAP--
'-----

'If you need to repeat a sequence of random numbers,
'you should call the Rnd function with a negative
'number as an argument immediately prior To using
'Randomize With any numeric argument.
Sub RepeatNumbers()
    Dim arr(9, 3)
    Dim loopCtr, intCtr
    Dim strMsg

    For loopCtr = 0 To 3
        Rnd -1
        Randomize(100)
        For intCtr = 0 To 9
            strMsg = strMsg & Rnd() & " "
        Next
        strMsg = strMsg & vbCrLf
    Next

    MsgBox strMsg
End Sub

'return reference to random open type0 cell
'this function will eventually have to timeout
Function RndOpenCell(arrCells)

    Dim c
    Set c = arrCells(RndInt(0, Ubound(arrCells)))
    If c.m_boolIsOpen Then
        'return c
        RndOpenCell = c
    Else
        'not found try again
        RndOpenCell = RndOpenCell(arrCells)
    End If

End Function

Option Explicit
'Script written by Josh Parker
'Script copyrighted by OPEN Architecture
'Script version Tuesday, February 15, 2011 3:25:36 AM

Class Village

    Private arrStructure
    Private arrTrees
    Private arrGrass
    Private arrPave

End Class

Class Snake

    Private oSpine
    Private oSkin

End Class

Class Skin

    Private arrScales

End Class

Class Spine

    'order array of pts
    Private arrCells

    'render snake method

End Class

Class Scale

    Private strType

```

```

Private oSrf
'maybe pointers to neighbors (ids)
'or shit maybe just reference the obj

End Class

```

UPLIFT HANGER, SOURCE CODE

Code written for Interactive paneling tool developed for use in design of structurally integrated prefabricated concrete panel system for design competition of airship hanger in anhui, china for competition submission completed in collaboration with OPEN Architecture and the Chinese Academy of Building Research (CABR)

Uses the following processing libraries:

controlP5 - gui toolkit

- <http://www.sojamo.de/libraries/controlP5/>

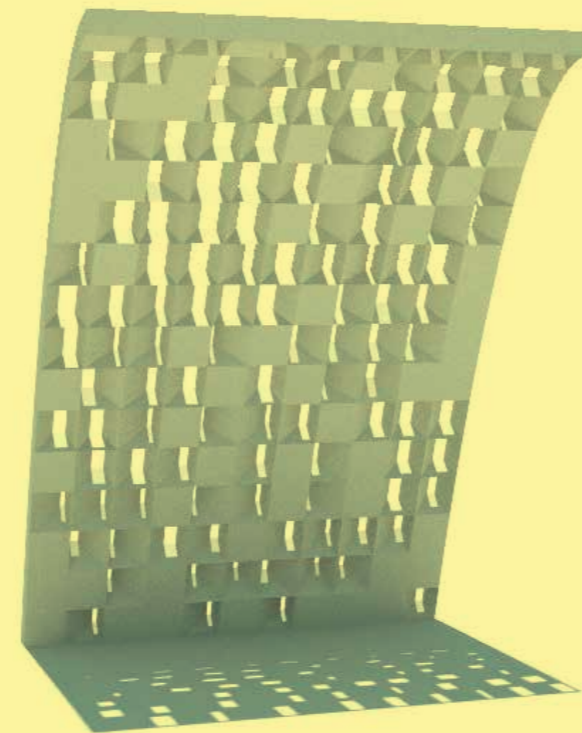
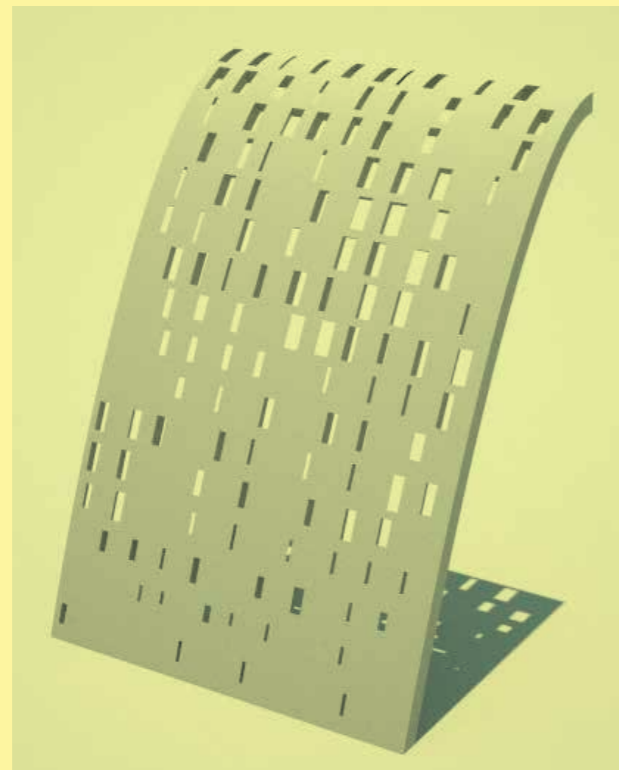
Proscene - 3d scene library

- <http://code.google.com/p/proscene/>

Objloader - 3d object loader

- <http://code.google.com/p/saitoobjloader/>

test sections of concrete massing generated by overlaying algorithmic patterns on top of solar data gathered from eco-tect.



```

/*****
Aper[n]atures
Author: Joshua Parker
Date: 2011

Interactive paneling tool developed for use in
design of structurally integrated prefabricated
concrete panel system for design competition
of airship hanger in anhui, china for competition
submission completed in collaboration with OPEN
Architecture and the Chinese Academy of Building
Research (CABR)

Implemented with Simple Model-View-Controller
(MVC) pattern:

Gui - is a wrapper for controlP5, which supplies
2d user interface toolkit
MyControlListener - receives ui events, ids and
routes them to controller
Controller - contains methods for updating data
model & controlling view(s)*
View - contains the scene(empty space and camera),
imported 3d base model, and data model defining
panel system. View calls draws to screen via
viewState interface, though only one ViewState
is implemented: View3d, a basic 3d view.
Hanger - data model defining panel system, composed
of subclass skin, which is composed of panels.
Panels are basically two sets of parameters: one
which defines the panel's size and position in
space, and another that defines the size and
relative position of a single rectangular void
in the panel. Panel also contains data from ecotect
about the amount of direct and diffuse radiation
each panel receives.

Uses the following processing libraries:

controlP5 - gui toolkit
- http://www.sojamo.de/libraries/controlP5/
Proscene - 3d scene library
- http://code.google.com/p/proscene/
Objloader - 3d object loader
- http://code.google.com/p/saitoobjloader/

Inherited License: GPL, V3

Fourth Natures Lab | www.fn1.com

*****/
import processing.core.*;
import controlP5.*;
import processing.opengl.*;
import controller.Listener;
import controller.Controller;
import model.Hanger;
import view.*;
import gui.*;

public class Apernatures extends PApplet{

    private static final long serialVersionUID = 1L;

    //CONSTANTS
    int U = 37; //number of modules in U direction
    int V = 42; //number of modules in V direction
    float D = 10f; //panel length/width dimension, D
(meters)
    float T = .5f; //thickness, T of frame (meters)
    float SUBDIVS = 20f; //subdivide panel for snapping

    //path to tabular data from ecotect analyses
    String PATH = "data/ecotectData.txt";

    //objects
    Listener myListener;
    Controller myController;
    Hanger myhanger;
    View myview;
    Gui mygui;

    public void setup(){
        size(1280, 1020, PGraphicsOpenGL.OPENGL);
        background(0);
        noStroke();

        //smooth();

        //MODEL: Parametric Data for panel system
        float snap = (float)((D-(T*2))/SUBDIVS);
        myhanger = new Hanger(this, U, V, D, T, snap,
        PATH);

        //VIEW: draws a representation of model to
        screen
        myview = new View(this, myhanger);

        //GUI: needs to access view scene for drawing 2d
        gui on top of 3d scene
        mygui = new Gui(this, myview);

        //CONTROLLER: updates model & views in response
        to ui events routed to it
        myController = new Controller(this, myhanger,
        mygui, myview);

        //LISTENER/ROUTER: receives ui events, ids and
        routes them to controller
        myListener = new Listener(this, myController);
    }

    public void draw(){
        background(50);

        //Continually redraw view and gui via controller
        myController.update();
    }

    //required to run as application
    public static void main(String args[]){
        PApplet.main(new String[] { "--present", "Apernat-
        ures" });
    }

    //send ui events to listener, so it route them to
    controller
    public void controlEvent(ControlEvent theEvent)
    {myListener.controlEvent(theEvent);}
    public void mousePressed(){myListener.
    mousePressed(mouseX, mouseY);}
    public void keyPressed(){myListener.
    keyPressed(key);}
}

Controller Class

MVC Controller contains methods for updating data
model & controlling view(s)*

Part of:
Aper[n]atures
Author: Joshua Parker
Date: 2011

Inherited License: GPL, V3

*****/
package controller;

import processing.core.PApplet;
import processing.core.PVector;
import model.Hanger;
import view.View;
import gui.Gui;

public class Controller{

    //The parent PApplet
    PApplet p;

    //PROPS
    private Hanger myhanger;
    private View myview;
    private Gui mygui;

    //CONSTRUCTOR
    public Controller(PApplet parent, Hanger Myhanger,
    Gui Mygui, View Myview){
        p = parent;
        myhanger = Myhanger;
        mygui = Mygui;
        myview = Myview;
    }

    // PUBLIC METHODS ///////////////////////////////////////////////////
    ///////////////////////////////////

    //gui noise increment
    public void setNoiseInc(float v){
        myhanger.setInc(v);
    }

    //set noise seed
    public void setNoiseSeed(int v){
        myhanger.setSeed(v);
    }

    //set coefficient with index i
    public void setPanelXcf(int i, float C){
        myhanger.setXcf(i, C);
    }

    //
    public void moveCameraByTheta(float v){
        PVector v0;
        float r = 500;
        float phi = 0;
        float theta = 0;
        //r = myview.scene.camera().sceneRadius();
        //r = 500;
        v0 = myview.scene.camera().position();
        phi = (float)Math.atan(v0.y/v0.x);
        theta = PApplet.radians(v); //azimuth 0-2PI
        setCameraPosition(phi, theta, r);
    }

    //
    public void moveCameraByPhi(float v){
        PVector v0;
        float r = 500;
        float phi = 0;
        float theta = 0;
        //r = myview.scene.camera().sceneRadius();
        //r = 500;
        v0 = myview.scene.camera().position();
        theta = (float)Math.acos(v0.z/r);
        phi = PApplet.radians(v); //azimuth 0-2PI
        setCameraPosition(phi, theta, r);
    }

    //
    public void setCameraPosition(float phi, float
    theta, float r){
        float x = r*(PApplet.sin(theta)*PApplet.
        cos(phi));
        float y = r*(PApplet.sin(theta)*PApplet.
        sin(phi));
        float z = r*PApplet.cos(theta);

        PVector v = new PVector(x,y,z);
        PVector v2 = new PVector(0,0,0);
        PVector v3 = new PVector(0,0,-1);

        myview.scene.camera().setPosition(v);
        myview.scene.camera().setOrientation(theta,
        phi);

        myview.scene.camera().setUpVector(v3,true);
        myview.scene.camera().lookAt(v2);
    }

    //
    public void focusGui(){
        myview.scene.disableMouseHandling();
        myview.scene.disableKeyboardHandling();
    }

    //
    public void focusScene(){
        myview.scene.enableMouseHandling();
        myview.scene.enableKeyboardHandling();
    }
}

```



```

////////////////////////////////////
//set view state
public void setViewState(ViewState newState){
    this.viewState = newState;
}

//get current fill
public boolean getFill(){
    return this.viewState.getFill();
}

//turn off strokes, turn on surface fill
public void enableFill(){
    this.viewState.enableFill();
}

//turn off surface fill, turn on strokes
public void disableFill(){
    this.viewState.disableFill();
}

//draw the view
public void draw() {
    this.viewState.draw();
}
}

View3d Class
View3d implements a basic 3d view

Part of:
Aper[na]tures
Author: Joshua Parker
Date: 2011

Inherited License: GPL, V3

*****
package view;

import processing.core.*;
import saito.objloader.*;
import model.*;

public class View3d implements ViewState{

    //The parent PApplet
    PApplet p;

    //composit view
    public View myview;

    //flags
    boolean bFill = false;

    //CONSTRUCTOR
    View3d(PApplet parent, View Myview){
        p = parent;
        this.myview = Myview;
    }

    // PUBLIC METHODS //////////////////////////////////////
    //////////////////////////////////////

    //turn off strokes, turn on surface fill
    public void enableFill(){
        bFill = true;
    }

    //turn off surface fill, turn on strokes
    public void disableFill(){
        bFill = false;
    }

    //get current fill
    public boolean getFill(){
        return bFill;
    }

    //draw the 3d view
    public void draw() {
        //setup lighting

```

```

-1);
//p.ambientLight(102, 102, 102);
p.lights();
p.stroke(10,10,10);

//set camera position and target
PVector v = new PVector(0,0,-1);
PVector v2 = new PVector(0,0,0);
myview.scene.camera().
    setUpVector(v,true);
myview.scene.camera().lookAt(v2);

//just want vertices so do not draw the
3d model!!! this will slow sketch way down
//myview.model.draw();

//load faces in array
Segment segment = myview.model.getSeg-
ment(0);
Face[] faces = segment.getFaces();

//for each face...
for (int i = faces.length-1; i >= 0;
i--) {

    //get face and corresponding
    panel
    Face nextFace = faces[i];
    Panel nextPanel = myview.my-
hanger.myskin.panels[i];

    //get vertices and normals of
    face and relative coordinates
    //of panel opening
    PVector[] vs = nextFace.get-
Vertices();
    PVector[] ns = nextFace.get-
Normals();
    PVector[] cs = nextPanel.co-
ords;

    //get panel color
    int clr = nextPanel.pClr;

    //map panel space coordinates
    to world space coordinates.
    PVector[] pts = mapFace(vs,
ns, cs);

    //stroke normal
    //line(vs[0].x, vs[0].y,
vs[0].z, vs[0].x+ns[0].x, vs[0].y+ns[0].y, vs[0].z+ns[0].z);

    //set fill and stroke
    if (bFill){
        p.fill(clr);
        p.noStroke();
    }else{
        p.noFill();
        p.stroke(10, 10,
10);
    }

    //draw four quad polygons
    p.beginShape();
    p.vertex(vs[0].x, vs[0].y,
vs[0].z);
    p.vertex(vs[1].x, vs[1].y,
vs[1].z);
    p.vertex(pts[1].x, pts[1].y,
pts[1].z);
    p.vertex(pts[0].x, pts[0].y,
pts[0].z);
    p.endShape();

    p.beginShape();
    p.vertex(vs[1].x, vs[1].y,
vs[1].z);
    p.vertex(vs[2].x, vs[2].y,
vs[2].z);
    p.vertex(pts[2].x, pts[2].y,
pts[2].z);
    p.vertex(pts[1].x, pts[1].y,
pts[1].z);
    p.endShape();

```

```

p.beginShape();
p.vertex(vs[2].x, vs[2].y,
vs[2].z);
p.vertex(vs[3].x, vs[3].y,
vs[3].z);
p.vertex(pts[3].x, pts[3].y,
pts[3].z);
p.vertex(pts[2].x, pts[2].y,
pts[2].z);
p.endShape();

p.beginShape();
p.vertex(vs[3].x, vs[3].y,
vs[3].z);
p.vertex(vs[0].x, vs[0].y,
vs[0].z);
p.vertex(pts[0].x, pts[0].y,
pts[0].z);
p.vertex(pts[3].x, pts[3].y,
pts[3].z);
p.endShape();

} //end for loop
} //end draw

// PRIVATE METHODS //////////////////////////////////////
////////////////////////////////////

//find hole vertices on face from a face
vertices(vs),
//face normals(ns), and face-space coordinates(cs)
private PVector[] mapFace(PVector[] vs, PVector[]
n, PVector[] cs){
    PVector[] pts = new PVector[0];

    //for each corner, map 2d coord to 3d pt
    for (int i = vs.length-1; i >= 0; i--) {
        PVector pt = mapPt(vs[0],
n[i], cs[i]);
        pts = (PVector[])PApplet.
append(pts, pt);
    }
    return pts;
}

//find single 3d pt from a vertice(v), normal(n),
//and 2d relative coordinate(c)
private PVector mapPt(PVector v, PVector n, PVec-
tor c){

    //get angle of normal
    float a = (float)Math.atan(n.z/n.y);
    a = PApplet.radians(90-PApplet.
abs(PApplet.degrees(a)));

    float x,y,z;

    if(n.y < 0){
        x = v.x + c.x;
        y = v.y - c.y*PApplet.cos(a);
        z = v.z - c.y*PApplet.sin(a);
    }else{
        x = v.x + c.x;
        y = v.y - c.y*PApplet.cos(a);
        z = v.z + c.y*PApplet.sin(a);
    }

    PVector pt3d = new PVector(x, y, z);

    return pt3d;
}

}

*****
ViewState Class
ViewState is an interface for various views

Part of:
Aper[na]tures
Author: Joshua Parker
Date: 2011

```

```

Inherited License: GPL, V3

*****
package view;

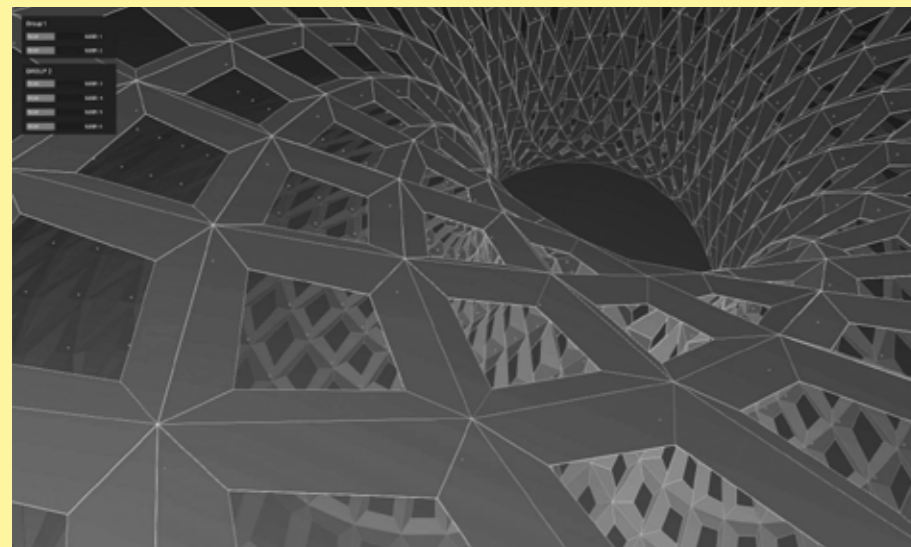
public interface ViewState{

    public void enableFill();
    public void disableFill();
    public boolean getFill();
    public void draw();
}

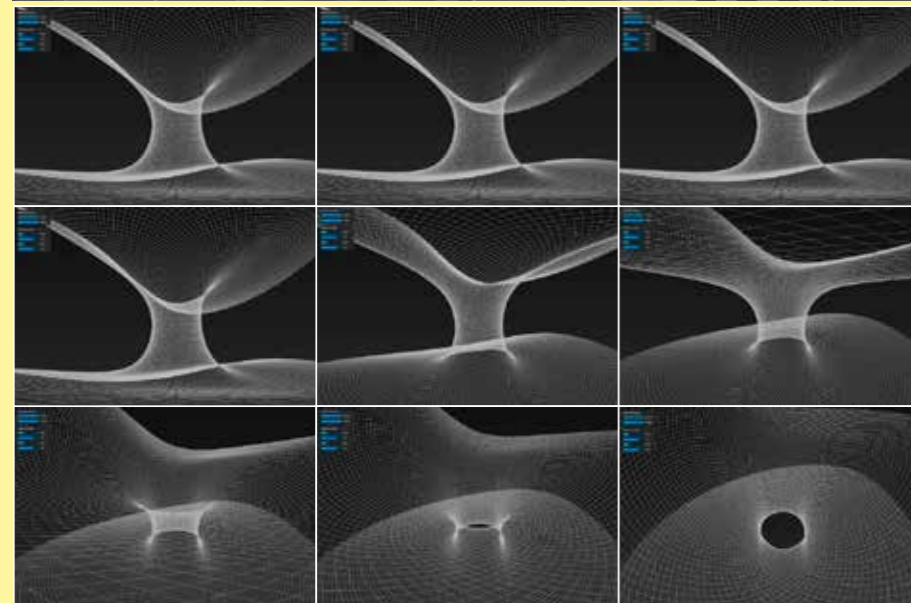
```

ZHUHAI PAVILION, SOURCE CODE

A CUSTOM PANELING TOOL WAS BUILT WITH JAVA/PROCESSING USING OPEN SOURCE GEOMETRY LIBRARY (IGEO, BY SATURO SUGIHARA) TO INTEROGATE FORM AND EXPLORE THE POSSIBILITY OF PERFORATING THE SHELL IN PLACES TO CREATE VISUAL AND PHYSICAL ACCESS THROUGH VERTICAL SURFACES. TOOL DEFINES A UV DIAGRAD AND MAPS PERFORATION PATTERNS AN INPUT SURFACE USING SIMPLE ALGORITHMS AND EXPOSES DESIGN PARAMETERS. THIS ALLOWED FOR REAL-TIME COLLABORATIVE USE BY ARCHITECTS, ENGINEERS, AND CLIENT.



gradient paneling condition
feedback to surface.



continuous surface subdivi-
sion.

```

/*****
DiagridPaneler

Author: Joshua Parker
Date: 2011

Uses the following processing libraries:

controlP5 - gui toolkit
- http://www.sojamo.de/libraries/controlP5/
Proscene - 3d scene library
- http://code.google.com/p/proscene/
Objloader - 3d object loader
- http://code.google.com/p/saitoobjloader/

Inherited License: GPL, V3

*****/
import igeo.*;
import processing.core.*;
import controlP5.*;
import processing.opengl.*;
import controller.Listener;
import controller.Controller;
import migeo.MyIG;
import migeo.MyPIGraphicsGL;
import model.Box;
import model.Model;
import view.*;
import gui.*;

public class DiagridPaneler extends PApplet{

    private static final long serialVersionUID = 1L;

    //path to tabular data from ecotect analyses
    String PATH = "data/ecotectData.txt";

    //objects
    Listener myListener;
    Controller myController;
    Model mymodel;
    View myview;
    Gui mygui;

    IG myig;

    public void setup(){
        size(1920, 1200, "migeo.MyPIGraphicsGL");
        //IG.bg(50, 40, 70, 90);
        IG.bg(255, 255, 255, 255);

        //MODEL: Parametric Data for panel system
        //mybox = new Box(this);
        mymodel = new Model(this);

        //VIEW: draws a representation of model to screen
        //NOTE: This is a representation of the data model ONLY!
        // It create shapes and geometry and igeo renders to
panel panes
        myview = new View(this, mymodel);

        //GUI: needs to access view scene for drawing 2d gui on top
of 3d scene
        //TBD: This should wrap all iu elements, ie. igeo panel,
        sidebar, etc.
        mygui = new Gui(this /*, IG.current().panel*/);

        //CONTROLLER: updates model & views in response to ui events
        routed to it
        myController = new Controller(this, mymodel, mygui, myview);

        //LISTENER/ROUTER: recieves ui events, ids and routes them to
        controller
        myListener = new Listener(this, myController);
    }

    public void draw(){
        //update model, view and gui via controller
        myController.update();
    }

    //required to run as application
    public static void main(String args[]) {
        PApplet.main(new String[] { "--present", "DiagridPaneler" });
    }
}

//send ui events to listener, so it can route them to control-
ler
public void controlEvent(ControlEvent theEvent){myListener.
controlEvent(theEvent);}
public void mousePressed(){myListener.mousePressed(mouseX,
mouseY);}
public void keyPressed(){myListener.keyPressed(key);}
}

/*****
Controller Class

MVC Controller contains methods for updating data
model & controlling view(s)*

Part of:

Aper[n]atures
Author: Joshua Parker
Date: 2011

Inherited License: GPL, V3

*****/
package controller;

import igeo.IG;
import processing.core.PApplet;
import processing.core.PVector;
//import model.Box;
import model.Model;
import view.View;
import gui.Gui;

public class Controller{

    //The parent PApplet
    PApplet p;

    //PROPS
    private Model mymodel;
    private View myview;
    private Gui mygui;

    //CONSTRUCTOR
    public Controller(PApplet parent, Model Mymodel, Gui Mygui,
View Myview){
        p = parent;
        mymodel = Mymodel;
        mygui = Mygui;
        myview = Myview;
    }

    // PUBLIC METHODS //////////////////////////////////////
    //

    public void setUCount(int n){
        //
        mymodel.unum = n;
    }

    //
    public void setVCount(int n){
        //
        mymodel.vnum = n;
    }

    //
    public void setPatternUStart(int v){
        //
        mymodel.uMin = (int) (v*.01*mymodel.unum);
    }

    //
    public void setPatternUStop(int v){
        //
        mymodel.uMax = (int) (v*.01*mymodel.unum);
    }
}

```

```

}
//
public void setPatternVStart(int v){
    //
    mymodel.vMin = (int) (v*.01*mymodel.vnum);
}
//
public void setPatternVStop(int v){
    //
    mymodel.vMax = (int) (v*.01*mymodel.vnum);
}

// PUBLIC METHODS //////////////////////////////////////
////////

//
public void focusGui(){
    //myview.scene.disableMouseHandling();
    //myview.scene.disableKeyboardHandling();
}

//
public void focusScene(){
    //myview.scene.enableMouseHandling();
    //myview.scene.enableKeyboardHandling();
}

//
public void toggleTexture(){
    /*if(!myview.bTexture){
        showTexture();
    } else {
        hideTexture();
    }*/
}

//
public void toggleMaterial(){
    if(!myview.bMaterial){
        showMaterial();
    } else {
        hideMaterial();
    }
}

//
public void toggleFill(){
    /*if(!myview.getFill()){
        showFill();
    } else {
        hideFill();
    }*/
}

//
public void showTexture(){
    //myview.model.enableTexture();
    //myview.bTexture = true;
}

//
public void hideTexture(){
    //myview.model.disableTexture();
    //myview.bTexture = false;
}

//
public void showMaterial(){
    //myview.model.enableMaterial();
    //myview.bMaterial = true;
}

//
public void hideMaterial(){
    //myview.model.disableMaterial();
    //myview.bMaterial = false;
}

//
public void showFill(){
    //myview.enableFill();
}

```

```

//
public void hideFill(){
    //myview.disableFill();
}
//
public void topView(){
    //IG.topView();
    IG.current().panel.currentPane().getView().setTop();
    //IG.view(0).setTop();
}
//
public void perspectiveView(){
    //IG.perspectiveView();
    IG.current().panel.currentPane().getView().setAxonomet-
ric();
}
//
public void gotoView1(){
    myview.setView1();
}
//
public void gotoView2(){
    myview.setView2();
}
//
public void update(){
    //mybox.update(); //update the model
    mymodel.update();
    myview.draw(); // draw the 3d scene
    mygui.draw(); // then draw the gui on top
}

}

Listener Class

Listener receives ui events, parses them and routes
them to controller for handling.

Part of:

Aper[na]tures
Author: Joshua Parker
Date: 2011

Inherited License: GPL, V3

*****/
package controller;

import igeo.IG;
import controlP5.ControlEvent;
import controlP5.ControlListener;
import processing.core.PApplet;

public class Listener implements ControlListener{
    //The parent PApplet
    PApplet p;

    //PROPS
    Controller myController;

    //CONSTRUCTOR
    public Listener(PApplet parent, Controller MyController){
        p = parent;
        myController = MyController;
    }

    // PUBLIC METHODS //////////////////////////////////////
    //////////

    //route slider events to controller via private handlers
    public void controlEvent(ControlEvent theEvent) {

        switch(theEvent.getController().getParent().getId()){
        case(0):
            //route g1 (shortcut info) event!
            g1ControlEvent(theEvent);
            break;

        case(1):
            //route g2 (noise sliders) event!
            g2ControlEvent(theEvent);
            break;

```

```

}

//route mouse events to controller
//this should be replaced with focus on hover
public void mousePressed(int mx, int my) {
    if (mx < 200) {
        myController.focusGui();
    } else {
        myController.focusScene();
    }
}

//route key press events to controller
public void keyPressed(char key) {

    if(key == 't') {
        //toggle the texture listed in .mtl file
        myController.toggleTexture();
    }
    else if(key == 'w') {
        //toggle the material listed in .mtl file
        //myController.toggleMaterial();
        //currentMousePane.getView().mode().
setDrawMode(true,false,false);
        IG.current().panel.currentPane().getView().
mode().setDrawMode(true,false,false);
    }
    else if(key == '0') {
        //toggle the fill for new shapes
        System.exit(0);
    }
    else if(key == '1') {
        //toggle the fill for new shapes
        myController.gotoView1();
    }
    else if(key == '2') {
        //toggle the fill for new shapes
        myController.gotoView2();
    }
    else if(key == 'a') {
        //toggle the fill for new shapes
        myController.topView();
    }
    else if(key == 's') {
        //toggle the fill for new shapes
        myController.perspectiveView();
    }
}

// PRIVATE METHODS //////////////////////////////////////
////////

//parse group 2 (noise sliders) event!
*****
private void g1ControlEvent(ControlEvent theEvent){

    float v;
    switch(theEvent.getController().getId()){
    case(1):
        v = theEvent.getController().getValue();
        myController.setUCount((int)(v));
        break;
    case(2):
        v = theEvent.getController().getValue();
        myController.setVCount((int)(v));
        break;
    }
}

//parse group 2 (noise sliders) event!
*****
private void g2ControlEvent(ControlEvent theEvent){

    float v;
    switch(theEvent.getController().getId()){
    case(4):
        v = theEvent.getController().getValue();
        myController.setPatternUStart((int)(v));
        break;
    case(5):
        v = theEvent.getController().getValue();
        myController.setPatternUStop((int)(v));
        break;
    case(6):
        v = theEvent.getController().getValue();

```

```

        myController.setPatternVStart((int)(v));
        break;
    case(7):
        v = theEvent.getController().getValue();
        myController.setPatternVStop((int)(v));
        break;
    }
}

package gui;

import igeo.IG;
import igeo.IVec;
import igeo.gui.IGraphicMode;
import igeo.gui.IGraphicMode.GraphicType;
import processing.core.PApplet;
import processing.core.PFont;
import controlP5.ControlP5;
import controlP5.Knob;

public class ControlPanel {
    //parent PApplet
    PApplet p;

    private ControlP5 cp5;

    //
    controlP5.Group[] groups;

    //count elements
    //int NumOfTabs;
    int numOfAccordings;
    int numOfGroups;
    int numOfElements;

    //current Elements
    //String curTab;
    //String curAccording;
    //String curGroup;
    //String curElement;

    int x;
    int y;
    int w;
    int h;

    int[] ppt = {0,0};
    int[] gpt = {0,0};
    int[] ept = {0,0};

    int dx;
    int dy;

    //style
    //int CPMargin;
    int marginTop = 40;
    int marginLeft = 20;
    int marginBottom = 10;
    int groupWidth = 200;
    //int groupHeight;
    //int accordingMargin;
    //int groupPadding;
    int headerPaddingTop = 10;
    int headerPaddingLeft = 5;
    int elementPaddingTop = 5;
    int elementPaddingLeft = 10;
    int elementWidth = 120;
    int elementHeight = 15;

    int BarH;
    int BgClr; //bg of block
    int BarClr; //bar color
    int HoverClr; //bar color on hover
    int LabelClr;

    int slideH;
    int slideW;
    int slideX;
    int slideSpC;
    int slideDY;
}

```

```

PFont arial;
PFont arial10;

//cp5 objs
//private Cp5UI cPanel;

public ControlPanel(int X, int Y, int W, int H, PApplet parent)
{
    p = parent;

    this.x = X;
    this.y = Y;
    this.w = W;
    this.h = H;

    gpt[0] = x;
    gpt[1] = y;

    this.dx = 25;
    this.dy = 30;

    cp5 = new ControlP5(p);
    cp5.setAutoDraw(false);

    numOfAccordings = 0;
    numOfGroups = 0;
    numOfElements = 0;

    groups = new controlP5.Group[2];

    BarH = 20;
    BgClr = p.color(50); //bg of block
    BarClr = p.color(50); //bar color
    HoverClr = 30; //bar color on hover
    LabelClr = p.color(255);

    slideH = 10;
    slideW = 100;
    slideX = 10;
    slideSpc = 5;
    slideDY = slideH+slideSpc;

    arial = p.createFont("ArialMT-30", 11);
    arial10 = p.createFont("ArialMT-30", 10);
}

// PUBLIC METHODS ////////////////////////////////////////////////////
/////

public void draw() {
    //switch to 2d draw gui, then switch back
    //also need to disable active pane so it
    //doesn't draw in lof4 grid pane in gridview
    disable3d();
    cp5.draw();
    enable3d();
}

// PRIVATE METHODS ////////////////////////////////////////////////////
/////

private void disable3d(){
    IGraphicMode mode2D = new IGraphicMode();
    mode2D.setGraphicType(GraphicType.J2D);
    //myview.panel.currentPane().getView().setMode(mode2D);
    IG.graphicMode(mode2D);
}

private void enable3d(){
    IGraphicMode modeGL = new IGraphicMode();
    modeGL.setGraphicType(GraphicType.GL);
    //myview.panel.currentPane().getView().setMode(modeGL);
    IG.graphicMode(modeGL);
}

//public void addTab(){
public void addAccording(){
}

//add group
public void addGroup(String name){
    //calc bgheight, placeholder for now <----!!!
    int bgHeight = 50;

    //
    groups[numOfGroups] = cp5.addGroup(name)
        .setId(numOfGroups)
        .setLabel(name)
        .setPosition(gpt[0] + marginLeft, gpt[1] + marginTop)
        .setWidth(groupWidth)
        //.setBackgroundHeight(bgHeight)
        .setBarHeight(BarH)
        .setBackgroundColor(BgClr)
        .setColorBackground(BarClr)
        .setColorForeground(HoverClr)
        .setColorLabel(LabelClr);

    numOfGroups++;

    gpt[1] = gpt[1] + elementHeight + marginTop;
    ept[0] = 0 + elementPaddingLeft;
    ept[1] = 0 + elementPaddingTop;

    //return this;
}

//add group
@SuppressWarnings("deprecation")
public void addGroup(String name){
    //calc bgheight, placeholder for now <----!!!
    //int bgHeight = 50;

    push();

    //
    groups[numOfGroups] = cp5.addGroup(name)
        .setId(numOfGroups)
        .setLabel(name)
        .setPosition(gpt[0], gpt[1])
        .setWidth(groupWidth)
        //.setBackgroundHeight(bgHeight)
        .setBarHeight(BarH)
        .setBackgroundColor(BgClr)
        .setColorBackground(BarClr)
        .setColorForeground(HoverClr)
        .setColorLabel(LabelClr)
        .hideBar();

    numOfGroups++;

    cp5.addTextLabel(name+"-label")
        .setId(numOfElements)
        .setText(name)
        .setHeight(elementHeight)
        .setPosition(ept[0]+headerPaddingLeft,
            ept[1]+headerPaddingTop)
        //.setColorValue(0xfffff00)
        .setFont(p.createFont("Arial-bold", 12))
        .moveTo(groups[numOfGroups-1]);

    numOfElements++;

    step();

    //return this;
}

public void endGroup(){
    //
    groups[numOfGroups-1].setBackgroundHeight(ept[1]);

    pop();
}

//add sep function for floating pt values
public void addSlider(String label, int minV, int maxV, int defaultV){
    cp5.addSlider(label)
        .setId(numOfElements)
        .moveTo(groups[numOfGroups-1])

```

```

        .setPosition(ept[0]+elementPaddingLeft,
            ept[1]+elementPaddingTop)
        .setSize(elementWidth,elementHeight)
        .setRange(minV,maxV)
        .setValue(defaultV);

    numOfElements++;

    step();
}

//add sep function for floating pt values
public void addSlider(String label, int minV, int maxV,
    int defaultV){
    //
    cp5.addSlider(label)
        .setId(numOfElements)
        .moveTo(groups[numOfGroups-1])
        .setPosition(ept[0],ept[1])
        .setSize(elementWidth,elementHeight)
        .setRange(minV,maxV)
        .setValue(defaultV);

    numOfElements++;

    gpt[1] = gpt[1] + elementHeight;
    ept[1] = ept[1] + elementHeight + elementPaddingTop;

    groups[numOfGroups-1].setBackgroundHeight(ept[1]
        + elementPaddingTop);
}

public void addKnob(String label, int minV, int maxV, int defaultV){
    //add to style sheet
    //...

    //
    cp5.addKnob(label)
        .setId(numOfElements)
        .moveTo(groups[numOfGroups-1])
        .setPosition(20,20)
        .setRadius(35)
        .setAngleRange(2*PApplet.PI)
        .setStartAngle((float)(.5*PApplet.PI))
        .setRange(minV,maxV)
        .setValue(defaultV)
        .setNumberOfTickMarks(16)
        .snapToTickMarks(true)
        .setColorForeground(p.color(255))
        .setColorBackground(p.color(40))
        .setColorActive(p.color(255,255,0))
        .setDragDirection(Knob.HORIZONTAL);

    numOfElements++;

    public void addTextArea(String label, String text){
        //add to style sheet
        //...

        //
        cp5.addTextArea(label)
            .moveTo(groups[numOfGroups-1])
            .setPosition(5,5)
            .setSize(195,90)
            .setFont(arial)
            .setLineHeight(14)
            .setColor(p.color(128))
            .setColorBackground(p.color(50))
            .setColorForeground(p.color(255,100))
            .setText(text);

    numOfElements++;

    private void push(){
        //push into group
        //gpt[0] += dx;
        //gpt[1] += dy;

```

```

//reset element registration pt
ept[0] = 0;
ept[1] = 0;

private void step(){
    //set to next element in group
    ept[1] += dy;
}

private void pop(){
    //pop out of group
    //gpt[0] -= dx;
    gpt[1] += ept[1] + marginBottom;
}

}

//*****
Gui Class

Gui is a wrapper for controlP5 library, which
provides user interface toolkit. more at:
http://www.sojamo.de/libraries/controlP5/

Part of:

Aper[n]atures
Author: Joshua Parker
Date: 2011

Inherited License: GPL, V3

*****/
package gui;

import igeo.IG;
import igeo.gui.IGraphicMode;
import igeo.gui.IGraphicMode.GraphicType;
import processing.core.PApplet;
import processing.core.PFont;
import controlP5.*;
//import remixlab.proscene.*;
//import view.*;

public class Gui
{
    //parent PApplet
    PApplet p;

    //cp5 objs
    private ControlPanel cPanel;

    //CONSTRUCTOR
    public Gui(PApplet parent){
        //initialize
        p = parent;

        cPanel = new ControlPanel(20,20, 200, p.height, p);

        cPanel.addGroup("Resample surface");
        cPanel.addSlider("u Samples", 5, 200, 20);
        cPanel.addSlider("v Samples", 5, 200, 20);
        cPanel.endGroup();
        cPanel.addGroup("Pattern u/v range");
        cPanel.addSlider("u start", 0, 100, 25);
        cPanel.addSlider("u stop", 0, 100, 75);
        cPanel.addSlider("v start", 0, 100, 25);
        cPanel.addSlider("v stop", 0, 100, 75);
        cPanel.endGroup();
    }

    // PUBLIC METHODS ////////////////////////////////////////////////////
    /////

    public void draw() {
        //switch to 2d draw gui, then switch back
        //also need to disable active pane so it
        //doesn't draw in lof4 grid pane in gridview
        disable3d();
        //
        cp5.draw();
        enable3d();

        cPanel.draw();
    }
}

```

```

    /** PRIVATE METHODS //////////////////////////////////////
    //////////////////////////////////////
    private void disable3d(){
        IGraphicMode mode2D = new IGraphicMode();
        mode2D.setGraphicType(GraphicType.J2D);
        //myview.panel.currentPane().getView().setMode(mode2D);
        IG.graphicMode(mode2D);
    }

    private void enable3d(){
        IGraphicMode modeGL = new IGraphicMode();
        modeGL.setGraphicType(GraphicType.GL);
        //myview.panel.currentPane().getView().setMode(modeGL);
        IG.graphicMode(modeGL);
    }

package migeo;

import igeo.IG;

public class MyIG extends IG{

    /** Processing Graphics using OpenGL to be put in size() method
    in Processing */
    public static final String GL = "igeo.p.MyPIGraphicsGL";

}

package migeo;

import java.awt.Color;

import javax.media.opengl.GL;

import processing.core.PApplet;

import com.sun.opengl.util.j2d.Overlay;

import igeo.IG;
import igeo.gui.IGraphicsGL;
import igeo.gui.IGridPanel;
import igeo.gui.IPaneLight;
import igeo.gui.IPanel;
import igeo.gui.IView;
import igeo.p.PICongfig;
import igeo.p.PIGraphicsGL;
import igeo.p.PIInput;

public class MyPIGraphicsGL extends PIGraphicsGL{

    //public PIGraphicsGL(){ super(); }
    public IPaneLight pane;

    /**
    setParent is called by Processing in the initialization process of
    Processing.
    Here the initialization proces of iGeo is also done.
    @param parent parent PApplet of Processing.
    */
    public void setParent(PApplet parent){
        super.setParent(parent);

        // initialize root GUI
        //panel = new IGridPanel(0,0,parent.getWidth(),parent.
getHeight(),2,2);
        panel = new IPanel(0,0,parent.getWidth(),parent.
getHeight());

        IView v=null;
        v = IView.getDefaultPerspectiveView(0,0,parent.
getWidth(),parent.getHeight());
        v.enableGL(); // here?
        v.enableRotationAroundTarget(); // here?
        v.setTarget(0,0,0); //

        pane = new IPaneLight(0,0,parent.getWidth(),parent.
getHeight(),v,pane);
        panel.addPane(pane);
        panel.currentMousePane = pane;

```

```

        panel.setVisible(true);

        // initialize iGeo
        IG ig = IG.init(panel);

        ig.server().graphicServer().enableGL(); //
        //ig.setBasePath(parent.sketchPath("")); // not sketch-
Path

        if(!parent.online){ // only when running local
            ig.setBasePath(parent.dataPath("")); // for default
            path to read/write files
        }

        ig.setInputWrapper(new PIInput(parent));

        parent.addMouseListener(panel);
        parent.addMouseMotionListener(panel);
        parent.addMouseWheelListener(panel);
        parent.addKeyListener(panel);
        parent.addFocusListener(panel);
        parent.addComponentListener(panel);

        //igg = new IGraphics();
        igg = new IGraphicsGL();

        //noSmooth();

        if(PICongfig.drawBeforeProcessing) parent.
registerPre(this);
        else parent.registerDraw(this);
        parent.registerPost(this);

        if(PICongfig.resizable){ parent.frame.setResizable(true);

        super.hints[DISABLE_OPENGL_2X_SMOOTH]=true; //
        super.hints[ENABLE_OPENGL_4X_SMOOTH]=true; //

        public void setGLProperties(){
            gl.glEnable(GL.GL_MULTISAMPLE); //
            gl.glEnable(GL.GL_POINT_SMOOTH); //
            gl.glEnable(GL.GL_LINE_SMOOTH); //
            gl.glEnable(GL.GL_POLYGON_SMOOTH); //

            gl.glEnable(GL.GL_ALPHA_TEST); //
            //gl.glEnable(GL.GL_BLEND); //
            //gl.glDisable(GL.GL_BLEND); //
            //gl.glBlendFunc(GL.GL_SRC_ALPHA, GL.GL_ONE_MINUS_SRC_
ALPHA); //
            //gl.glBlendFunc(GL.GL_SRC_ALPHA, GL.GL_ONE); //

            gl.glHint(GL.GL_LINE_SMOOTH_HINT, GL.GL_NICEST); //
            gl.glHint(GL.GL_POINT_SMOOTH_HINT, GL.GL_NICEST); //
            gl.glHint(GL.GL_POLYGON_SMOOTH_HINT, GL.GL_NICEST); //

            //gl.glEnable(GL.GL_NORMALIZE); //
            //gl.glEnable(GL.GL_AUTO_NORMAL); //
            //gl.glShadeModel(GL.GL_SMOOTH); //

            //gl.glLightModel1(GL.GL_LIGHT_MODEL_TWO_SIDE, 1); //

            //gl.glEnable(GL.GL_DEPTH_TEST); // already enabled in
            //gl.glDisable(GL.GL_DEPTH_TEST); // ? for transparency

            //gl.glEnable(GL.GL_LIGHTING); // test!
            //gl.glEnable(GL.GL_LIGHT1); // test!

        }

        public void pre(){ drawIG(); }
        public void draw(){ drawIG(); }

        /**
        Drawing all the iGeo objects through IPanel.
        Overlay is also used to draw 2D graphics on top of OpenGL
        3D graphics.
        */
        public synchronized void drawIG(){
            int[] viewport=null;
            if(PICongfig.restoreGLViewport){
                viewport = new int[4];

```

```

                gl.glGetIntegerv(GL.GL_VIEWPORT, viewport, 0);
            }

            gl.glMatrixMode(GL.GL_MODELVIEW);
            gl.glPushMatrix();

            gl.glMatrixMode(GL.GL_PROJECTION);
            gl.glPushMatrix();

            if(PICongfig.resetGLDepthBefore) gl.glClear(GL.GL_DEPTH_
BUFFER_BIT);

            //gl.glClear(GL.GL_COLOR_BUFFER_BIT | GL.GL_DEPTH_BUF-
FER_BIT);

            //gl.glClear(GL.GL_COLOR_BUFFER_BIT);

            setGLProperties();

            if(igg.getGraphics()==null){
                setOverlay();
            }

            //igg.setGraphics(overlay.createGraphics());

            igg.getGraphics().clearRect(0,0,parent.
getWidth(),parent.getHeight()); //

            //overlay = new Overlay(drawable); //
            //Graphics2D g = overlay.createGraphics();
            //igg.setGraphics(g);

            igg.setGL(gl);

            panel.draw(igg);

            if(PICongfig.resetGLDepthAfter) gl.glClear(GL.GL_DEPTH_
BUFFER_BIT);

            gl.glMatrixMode(GL.GL_PROJECTION);
            gl.glPopMatrix();

            gl.glMatrixMode(GL.GL_MODELVIEW);
            gl.glPopMatrix();

            // bring the original viewport back
            if(PICongfig.restoreGLViewport && viewport!=null){
                gl.glViewport(viewport[0], viewport[1], view-
port[2], viewport[3]);
            }

            if(overlay!=null){
                overlay.markDirty(0,0,parent.getWidth(),parent.
getHeight());
                overlay.drawAll();
            }

            //g.dispose();
            //igg.getGraphics().dispose();

        }

        public void setOverlay(){
            overlay = new Overlay(drawable); //
            igg.setGraphics(overlay.createGraphics());
            igg.getGraphics().setBackground(overlayBG);
        }

        public void setSize(int w, int h){
            super.setSize(w,h);
            setOverlay(); // update overlay
        }

        public void post(){
            if(overwritePAppletFinish) parent.finished=finished;
            if(overwritePAppletLoop) if(looping) parent.loop();
            else parent.noLoop();
        }

        public void loop(){ if(!looping) looping=true; }
        public void noLoop(){ if(looping) looping=false; }

        public void start(){ if(finished) finished=false; }
        public void stop(){ if(!finished) finished=true; }

```

```

        /**
        public void mousePressed(MouseEvent e){
        }
        public void mouseReleased(MouseEvent e){
        }
        public void mouseClicked(MouseEvent e){
        }
        public void mouseEntered(MouseEvent e){
        }
        public void mouseExited(MouseEvent e){
        }
        public void mouseMoved(MouseEvent e){
        }
        public void mouseDragged(MouseEvent e){
        }
        public void mouseWheelMoved(MouseWheelEvent e){
        }
        public void keyPressed(KeyEvent e){
        }
        public void keyReleased(KeyEvent e){
        }
        public void keyTyped(KeyEvent e){
        }
        public void focusLost(FocusEvent e){
        }
        public void focusGained(FocusEvent e){
        }
        */
        /**
        public void componentHidden(ComponentEvent e){
        }
        public void componentMoved(ComponentEvent e){
        }
        public synchronized void componentResized(ComponentEvent e){
            int w = e.getComponent().getBounds().width;
            int h = e.getComponent().getBounds().height;
            setSize(w,h);
        }
        public void componentShown(ComponentEvent e){
        }
        */

        /*****
        FramePanel Class

        Part of:

        Aper[n]atures
        Author: Joshua Parker
        Date: 2011

        Inherited License: GPL, V3

        *****/
        package model;

        import igeo.IVec;
        import processing.core.PApplet;

        public class FramePanel {

            //The parent PApplet
            PApplet p;

            double MAXTHICK = .2;

            public IVec center;
            public IVec normal;
            public IVec[] corners = new IVec[4];
            public double openness; //0.0 - 1.0
            public double thinness; //0.0 - 1.0

            public IVec[] pts = new IVec[5];
            public IVec[] normals = new IVec[5];

            public FramePanel(IVec[] Pts, IVec[] Normals, double Openness,
PApplet parent){

                p = parent;

                //pts = Pts;
                //normals = Normals;

                center = Pts[0].dup();

```



```

import igeo.IG;
import igeo.IMesh;
import igeo.IPoint;
import igeo.ISurface;
import igeo.IVec;

public class View2 implements ViewState{

    //The parent PApplet
    PApplet p;

    //composit view
    public View view;
    public Model model;

    //CONSTRUCTOR
    View2(PApplet parent, View Myview){

        p = parent;

        this.view = Myview;

        //moved to model...
    }

    // PUBLIC METHODS //////////////////////////////////////
    //draw the 3d view
    public void draw() {

        //clear geometry in the scene
        IG.cur().server().clear();
        IG.bg(25, 25, 50, 50);

        //draw
        for(FramePanel panel : view.mymodel.panels){

            new ICurve(panel.corners[0], panel.corners[1]).
clr(150);
            new ICurve(panel.corners[1], panel.corners[2]).
clr(150);
        }

        //end draw

    // PRIVATE METHODS //////////////////////////////////////
    }
    /*****

ViewState Class

ViewState is an interface for various views

Part of:

Aper[na]tures
Author: Joshua Parker
Date: 2011

Inherited License: GPL, V3

*****/
package view;

public interface ViewState{

    //public void enableFill();
    //public void disableFill();
    //public boolean getFill();
    public void draw();
}

```

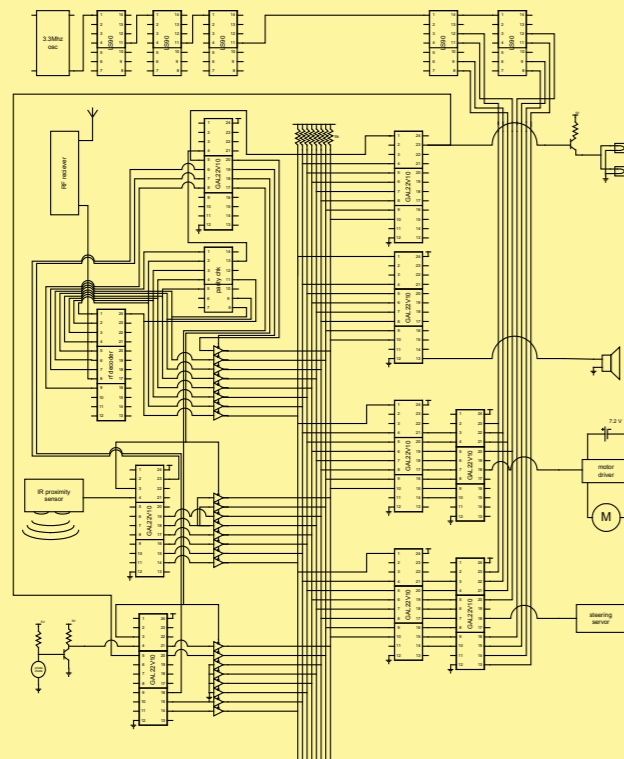
BEING THERE, SOURCE CODE

THE CAR PROJECT CONSISTS OF TWO MAIN MODULES. ONE OF THE MAIN MODULES IN THE USER INTERFACE CIRCUIT WHICH HANDLES ALL DATA COMING IN FROM THE USER AND SENDS IT OFF TO THE RF TRANSMITTER. THE OTHER MAIN MODULE RECEIVES THE INCOMING DATA FROM THREE SEPARATE SOURCES: THE RF RECEIVER, LIGHT SENSOR, AND PROXIMITY SENSOR. USING THESE SIGNALS IT CAN SUCCESSFULLY CONTROL THE STEERING, HORN, LIGHTS, AND MOTOR. THE LATTER CIRCUIT IS ACTUALLY ON THE RC CAR. THE USER WILL ALSO HAVE A REAL-TIME VIDEO FEED AVAILABLE TO BE ABLE TO WATCH WHERE THEY ARE GOING. THIS TRANSLATES TO A RC CAR CONTROLLED BY THE USER VIA VIDEO GAME CONTROLLER. THE STEERING WHEEL CONTROLLER WILL SEND DATA TO A PIC MICROCONTROLLER, WHICH WILL BE THE MAIN CONTROL UNIT ON THE USER SIDE OF THE SYSTEM. A DIGITAL READOUT OF THE CURRENT GEAR AND WELL AS STATUS LIGHTS WILL BE PRESENT. SRAM WILL BE AVAILABLE TO RECORD INPUT FROM THE USER. THE CAR WILL RESPOND TO COMMANDS BY THE USER VIA RF COMMUNICATION.

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MATT ZOBEL

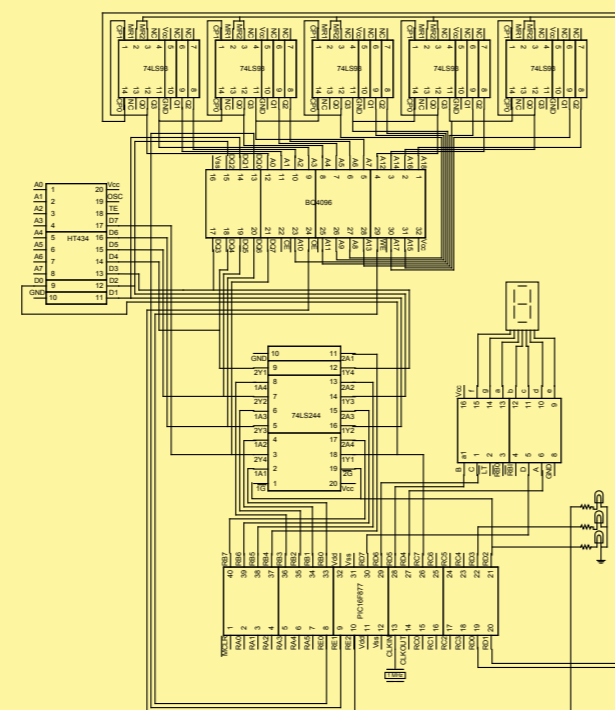
ADVISORS:
JAMES K. PECKOL

1. main board schematic
2. control board schematic



* Motor runs counter against control for safety
** All signals are active low, and ground is 0V
*** All signals are active low

1.



2.

The user module is controlled by the PIC microcontroller. The PIC accepts user input via the steering wheel, gas pedal, brake pedal, and buttons. Since the wheel, and pedals are potentiometer devices the PIC sample these measurements using the internal A/D converter. These measurements are then encoded internally in the PIC to compress some of the bits that are used. The PIC samples these devices continually and sends out three separate frames in sequence over RF transmission. The first frame contains speed information, the second contains turning information, and the third contains button push information.

To help detect errors a parity checker is used to calculate even parity and the parity bit is sent along with the transmission. The frames are sent to the RF encoder and then onto the RF transmitter for transmission to the car at 434MHz.

The PIC also controls some user displays according to the current state of the car. There is a gear display near the user that display the current gear the car is in. The PIC will increment or decrement the gear according to user input. The valid gears are 1,2,3,and R. In addition, the PIC controls 3 LED's that indicate the current status of the memory. The Green LED indicates that the car is under control of the user. The yellow LED indicates the memory is currently being written to. The Red LED means the memory is being read, nullifying any user input.

To control the memory the PIC uses 5 cascaded 74LS93 chips for addressing. The PIC sends out clock signals to the 74LS93 chips to increment them each time an address is written or read. The PIC is also responsible for clocking the SRAM to look at the current address and either read or write and is responsible for adding a flag bit to the last instruction written to memory. This is all done via the 8 bit parallel bus.

The car receives the data from the user module via RF transmission at 434MHz. The incoming data is sent through the RF decoder and onto the bus and into the parity checker. The Bus Master waits to get a valid transmit signal from the RF decoder. When Bus Master sees this signal he makes sure that the parity was correct. If so he strobes everyone listening to the bus to capture the new information.

Bus Master is also in charge of flipping the bus around when the proximity sensor chip or the light sensor chip have something to write to the bus. When the requests are made the Bus Master will flip the bus at the appropriate time and then flip it back when they are done.

After the Bus Master strobes the other nodes to capture the information on the bus, each node looks at the type of frame it is, as shown

on Figure 5. Using bits 6 and 7 each node knows what type of frame to look at, if it is the wrong frame, it just ignores it. Speed decoder, steering decoder, horn controller, and light controller all listen to the bus continually.

Speed decoder and steering decoder decode the five-bit data stream in a speed frame or steering frame. With the input from the bus they decode the data into an eight-bit BCD value corresponding to the actual PWM signal that the generators will generate. For example, in a steering frame a 10000 sent by the user module gets decoded into a 42% duty cycle, therefore, the module puts out a 4 and 2 in BCD. The generators use 2 cascaded 74LS90 chips that are counting in BCD to do a comparison on. When the BCD input equals the BCD count, the PWM signal goes down and a PWM generation is produced.

The proximity sensor node and light sensor node have a little more intelligence. These nodes are responsible for writing to the bus to control the four nodes that are listening. If the light sensor senses a discrepancy between the status of the light and the status of the sensor, the light sensor node asks the bus master for bus control. When the control is granted the light sensor will write information to the bus to turn the light on or off appropriately.

he proximity sensor node works similarly to the light sensor. When the node receives information that the car is near a wall the node asks for control of the bus. When the control is granted, the proximity sensor node writes information to the bus, then to the speed controller, telling it to throw it into reverse. When the wall is no longer detected the proximity sensor then writes to the bus again telling the speed controller to go to idle. It must be noted that the bus is completely tied up by the proximity sensor node when the wall is near the car.

Using this implementation resulted in a successful project that operated correctly. Timing was the key ingredient and although we had some issues with timing in the beginning, in the end, it worked very well.

CUPL CODE

Busmaster.pld

Name busmstr;
Partno GAL22V10;
Date 05/06/02;
Revision XX;
Designer XXXXX;
Company XXXXX;
Assembly XXXXX;
Location XXXXX;
Device g22v10;

WINDOW/UNKNOWN

Inputs

Pin 1 = clk;
Pin 2 = reset;
Pin 4 = parity;
Pin 5 = strobein;
Pin 6 = proxsense;
Pin 7 = lightsense;
Pin 8 = validtransmit;

Outputs

Pin 17 = lightenable;
Pin 18 = proxenable;
Pin 19 = mstrenable;
Pin 20 = strobeout;
Pin [21..23] = [s2..s0];

FIELD buscntrl = [s2..s0];

DEFINITIONS for idle, paritycheck, strobe, proxdetect, proxwait, lightdetect, lightwait, proxdetect2

Declarations and Intermediate Variable Definitions

s0.ar = reset;
s1.ar = reset;
s2.ar = reset;

s0.sp = 'b'0;
s1.sp = 'b'0;
s2.sp = 'b'0;

s0.oe = 'b'1;
s1.oe = 'b'1;
s2.oe = 'b'1;

sequence buscntrl
{
present idle /* 000 */
default
next idle;
if(proxsense)
next proxdetect;
if(validtransmit & !proxsense)
next paritycheck;
if(lightsense & !proxsense & !strobein)
next lightdetect;

present paritycheck /* 001 */
default
next paritycheck;
if(proxsense)
next proxdetect;
if(!parity & !proxsense)
next idle;
if(parity & !proxsense)
next strobe;
present strobe /* 010 */
default
next idle;
if(proxsense)
next proxdetect;
present proxdetect /* 011 */
default
next proxdetect;
if(strobein)
next proxdetect2;
present proxdetect2 /* 111 */
default
next proxdetect2;
if(strobein)
next proxwait;
present proxwait /* 100 */
default
next idle;
present lightdetect /* 101 */
default
next lightdetect;
if(proxsense)
next proxdetect;
if(strobein & !proxsense)
next lightwait;
present lightwait /* 110 */
default
next idle;

Logic Equations

idl = !s2 & !s1 & !s0;
parchk = !s2 & !s1 & s0;
str = !s2 & s1 & !s0;
proxd = !s2 & s1 & s0;
proxd2 = s2 & s1 & s0;
proxw = s2 & !s1 & !s0;
lightd = s2 & !s1 & s0;
lightw = s2 & s1 & !s0;

strobeout = str;
mstrenable = !(idl # parchk # str); /* Drive Tri-State--Low Enable */
proxenable = !(proxd # proxw # proxd2); /* Drive Tri-State--Low Enable */
lightenable = !(lightd # lightw);

honker.pld

Name honker;
Partno GAL22V10;
Date 05/27/02;
Revision XX;
Designer XXXXX;
Company XXXXX;
Assembly XXXXX;
Location XXXXX;
Device g22v10;

WINDOW/UNKNOWN

Inputs

Pin 1 = clk;

Pin 2 = reset;
Pin 3 = strobe;
Pin [4..10] = [bus1..bus7];

Outputs

Pin 13 = out_freq;
Pin 22 = s0;
Pin 23 = honkactive;

FIELD buscntrl = [s0];

DEFINITIONS for off, on

Declarations and Intermediate Variable Definitions

s0.ar = reset;
s0.sp = 'b'0;
s0.oe = 'b'1;

sequence buscntrl

present off
default
next off;
if(strobe & bus2 & bus7 & !bus6)
present on
default
next on;
if(strobe & !bus2 & bus7 & !bus6)
next off;

Logic Equations

honkactive = s0 & out_freq;

lighter.pld

Name lighter;
Partno GAL22V10;
Date 05/27/02;
Revision XX;
Designer XXXXX;
Company XXXXX;
Assembly XXXXX;
Location XXXXX;
Device g22v10;

WINDOW/UNKNOWN

Inputs

Pin 1 = clk;
Pin 2 = reset;
Pin 3 = strobe;
Pin [4..10] = [bus1..bus7];

Outputs

Pin 22 = s0;
Pin 23 = lightactive;

FIELD buscntrl = [s0];

DEFINITIONS for off, on

Declarations and Intermediate Variable Definitions

s0.ar = reset;
s0.sp = 'b'0;
s0.oe = 'b'1;

sequence buscntrl

present off
default
next off;
if(strobe & bus1 & bus7 & !bus6)
present on
default
next on;
if(strobe & bus1 & bus7 & !bus6)
next off;

Logic Equations

lightactive = s0;

lightsense.pld

Name lsense;
Partno GAL22V10;
Date 05/06/02;
Revision XX;
Designer XXXXX;
Company XXXXX;
Assembly XXXXX;
Location XXXXX;
Device g22v10;

WINDOW/UNKNOWN

Inputs

Pin 1 = clk;
Pin 2 = reset;
Pin 3 = !flipenable;
Pin 4 = !lightsense;
Pin 5 = lightstatus;
Pin 6 = honkstatus;

Outputs

Pin 14 = strobe;
Pin 15 = bus1;
Pin 16 = bus2;
Pin 17 = fliprequest;
Pin [18..20] = [s0..2];
Pin 21 = bus6;
Pin 22 = bus7;

FIELD lightcntrl = [s2..s0];

DEFINITIONS for idle, flipreq, datasend, strobey, wait

Declarations and Intermediate Variable Definitions

s0.ar = reset;
s1.ar = reset;
s2.ar = reset;

s0.sp = 'b'0;
s1.sp = 'b'0;
s2.sp = 'b'0;

```

s0.oe = 'b'1;
s1.oe = 'b'1;
s2.oe = 'b'1;

sequence lightcntrl
{
    present idle
    default
next idle;
    if((lightsense $ lightstatus))
next flipreq;

    present flipreq
    default
next flipreq;
    if(flipenable)
next datasend;

    present datasend
    default
next strobey;

    present strobey
    default
next wait;

    present wait
    default
next idle;
}

/** Logic Equations **/

strobe = !s2 & s1 & s0;
bus1 = 'b'1;
bus2 = honkstatus;
bus6 = 'b'0;
bus7 = 'b'1;
fliprequest = !s2 & !s1 & s0;

Proximity Sense.pld

Name psense;
Partno GAL22V10;
Date 05/06/02;
Revision XX;
Designer XXXXX;
Company XXXXX;
Assembly XXXXX;
Location XXXXX;
Device g22v10;

/*****
/* WINDOW/UNKNOWN */
/* */
*****/

/** Inputs **/

Pin 1 = clk;
Pin 2 = reset;
Pin 3 = !flipenable;
Pin 4 = proxsense;

/** Outputs **/

Pin 14 = strobe;
Pin [15..19] = [bus1..5]; /* Tie Bus 6 & 7 to Pin 18 */
Pin [20..22] = [s0..2];
Pin 23 = fliprequest;

FIELD proxcntrl = [s2..s0];

$DEFINE idle 'b'000
$DEFINE flipreq 'b'001

```

```

$DEFINE rev_send 'b'010
$DEFINE rev_stroby 'b'011
$DEFINE rev_wait 'b'100
$DEFINE idle_send 'b'101
$DEFINE idle_stroby 'b'110
$DEFINE idle_wait 'b'111

/** Declarations and Intermediate Variable Definitions **/

s0.ar = reset;
s1.ar = reset;
s2.ar = reset;

s0.sp = 'b'0;
s1.sp = 'b'0;
s2.sp = 'b'0;

s0.oe = 'b'1;
s1.oe = 'b'1;
s2.oe = 'b'1;

sequence proxcntrl
{
    present idle
    default
next idle;
    if(proxsense)
next flipreq;

    present flipreq
    default
next flipreq;
    if(flipenable)
next rev_send;

    present rev_send
    default
next rev_stroby;

    present rev_stroby
    default
next rev_wait;

    present rev_wait
    default
next rev_wait;
    if(!proxsense)
next idle_send;

    present idle_send
    default
next idle_stroby;

    present idle_stroby
    default
next idle_wait;

    present idle_wait
    default
next idle;
}

/** Logic Equations **/

strobe = (!s2 & s1 & s0) # (s2 & s1 & !s0);
bus1 = 'b'0;
bus2 = (!s2 & s1 & !s0) # (!s2 & s1 & s0) # (s2 & !s1 & !s0);
bus3 = (!s2 & s1 & !s0) # (!s2 & s1 & s0) # (s2 & !s1 & !s0);
bus4 = 'b'0;
bus5 = (s2 & !s1 & s0) # (s2 & s1 & !s0) # (s2 & s1 & s0);
fliprequest = !s2 & !s1 & s0;

Speed Generator.pld

Name spedpw90;
Partno GAL22V10;

```

```

Date 05/27/02;
Revision XX;
Designer XXXXX;
Company XXXXX;
Assembly XXXXX;
Location XXXXX;
Device g22v10;

/*****
/* WINDOW/UNKNOWN */
/* */
*****/

/** Inputs **/

Pin 1 = clk;
Pin 2 = reset;

Pin [3..6] = [MSB3..MSB0];
Pin [7..10] = [LSB3..LSB0];
Pin [13..16] = [clkMSB0..clkMSB3];
Pin [20..23] = [clkLSB0..clkLSB3];

/** Outputs **/
Pin 18 = !a0; /* this is the PWM output to the motor */
Pin 19 = temp;

FIELD pwm = [a0];

/** Declarations and Intermediate Variable Definitions **/

a0.ar = reset;
a0.sp = 'b'0;
a0.oe = !reset;

temp = (LSB0 $ clkLSB0) #
(LSB1 $ clkLSB1) #
(LSB2 $ clkLSB2) #
(LSB3 $ clkLSB3) #
(MSB0 $ clkMSB0);

sequence pwm
{
    present 'b'0
    default
next 'b'0;
    if(! temp #
(MSB1 $ clkMSB1) #
(MSB2 $ clkMSB2) #
(MSB3 $ clkMSB3) ))
next 'b'1;

    present 'b'1
    default
next 'b'1;
    if(!clkLSB0 & !clkLSB1 & !clkLSB2 & !clkLSB3 &
!clkMSB0 & !clkMSB1 & !clkMSB2 & !clkMSB3)
next 'b'0;
}

Speed Decoder.pld

Name speeder;
Partno GAL22V10;
Date 05/27/02;
Revision XX;
Designer XXXXX;
Company XXXXX;
Assembly XXXXX;
Location XXXXX;
Device g22v10;

/*****
/* WINDOW/UNKNOWN */
/* */
*****/

```

```

/** Inputs **/

Pin 1 = clk; /* this is the Strobe off the
bus, bus bit 0 */
Pin 2 = reset;

Pin [4..10] = [bus1..bus7];

/** Outputs **/

Pin [14..17] = [LSBdutydcycle0..LSBdutydcycle3];
Pin [18..21] = [MSBdutydcycle0..MSBdutydcycle3];

/* intermediates */

MSBdutydcycle3.ar = reset;
MSBdutydcycle2.ar = reset;
MSBdutydcycle1.ar = reset;
MSBdutydcycle0.ar = reset;

LSBdutydcycle3.ar = reset;
LSBdutydcycle2.ar = reset;
LSBdutydcycle1.ar = reset;
LSBdutydcycle0.ar = reset;

MSBdutydcycle3.sp = 'b'0;
MSBdutydcycle2.sp = 'b'0;
MSBdutydcycle1.sp = 'b'0;
MSBdutydcycle0.sp = 'b'0;

LSBdutydcycle3.sp = 'b'0;
LSBdutydcycle2.sp = 'b'0;
LSBdutydcycle1.sp = 'b'0;
LSBdutydcycle0.sp = 'b'0;

MSBdutydcycle3.oe = 'b'1;
MSBdutydcycle2.oe = 'b'1;
MSBdutydcycle1.oe = 'b'1;
MSBdutydcycle0.oe = 'b'1;

LSBdutydcycle3.oe = 'b'1;
LSBdutydcycle2.oe = 'b'1;
LSBdutydcycle1.oe = 'b'1;
LSBdutydcycle0.oe = 'b'1;

speed_frame = !bus6 & !bus7; /* Speed Frame, 00 */

MSBdutydcycle3.d = (speed_frame & 'b'0) # (!speed_frame & MSBdutydcycle3);
MSBdutydcycle2.d = (speed_frame & 'b'1) # (!speed_frame & MSBdutydcycle2);
MSBdutydcycle1.d = (speed_frame & ( bus5 & bus4 & (bus3 # bus2))) # (!speed_frame & MSBdutydcycle1);
MSBdutydcycle0.d = (speed_frame & ( bus5 & (!bus4 # (bus4 & !bus3 & !bus2)))) # (!speed_frame & MSBdutydcycle0);

LSBdutydcycle3.d = (speed_frame & ( bus5 & bus4 & !bus3 & !bus2))) # (!speed_frame & LSBdutydcycle3);
LSBdutydcycle2.d = (speed_frame & ( bus3 & (!bus4 # bus2))) # (!speed_frame & LSBdutydcycle2);
LSBdutydcycle1.d = (speed_frame & ( (!bus4 & bus2) # (bus4 & bus3 & !bus2))) # (!speed_frame & LSBdutydcycle1);
LSBdutydcycle0.d = (speed_frame & ( bus1)) # (!speed_frame & LSBdutydcycle0);

Steering Decoder.pld

Name steerer;
Partno GAL22V10;
Date 05/27/02;
Revision XX;
Designer XXXXX;
Company XXXXX;
Assembly XXXXX;

```

```

Location XXXXX;
Device g22v10;

/*****
/*
/* WINDOW/UNKNOWN */
/*
*****/

/** Inputs **/

Pin 1 = clk; /* this is the Strobe off the
bus, bus bit 0 */
Pin 2 = reset;

Pin [4..10] = [bus1..bus7];

/** Outputs **/

Pin [14..17] = [LSBduty0..LSBduty3];
Pin [18..21] = [MSBduty0..MSBduty3];

MSBduty3.ar = reset;
MSBduty2.ar = reset;
MSBduty1.ar = reset;
MSBduty0.ar = reset;

LSBduty3.ar = reset;
LSBduty2.ar = reset;
LSBduty1.ar = reset;
LSBduty0.ar = reset;

MSBduty3.sp = 'b'0;
MSBduty2.sp = 'b'0;
MSBduty1.sp = 'b'0;
MSBduty0.sp = 'b'0;

LSBduty3.sp = 'b'0;
LSBduty2.sp = 'b'0;
LSBduty1.sp = 'b'0;
LSBduty0.sp = 'b'0;

MSBduty3.oe = 'b'1;
MSBduty2.oe = 'b'1;
MSBduty1.oe = 'b'1;
MSBduty0.oe = 'b'1;

LSBduty3.oe = 'b'1;
LSBduty2.oe = 'b'1;
LSBduty1.oe = 'b'1;
LSBduty0.oe = 'b'1;

steering_frame = bus6 & !bus7; /* Directional Frame, 01 */

MSBduty3.d = (steering_frame & 'b'0) # (!steering_frame & MSBduty3);
MSBduty2.d = (steering_frame & bus5) # (!steering_frame & MSBduty2);
MSBduty1.d = (steering_frame & !bus5) # (!steering_frame & MSBduty1);
MSBduty0.d = (steering_frame & (!bus5 & (bus4 # (bus3 & bus2))) # (bus5 & bus4 & (bus3 # bus2))) # (!steering_frame & MSBduty0);

LSBduty3.d = (steering_frame & (bus5 & bus4 & !bus3 & !bus2) # (!bus5 & !bus4 & bus3 & !bus2) # (!bus5 & bus4 & bus3 & bus2)) # (!steering_frame & LSBduty3);
LSBduty2.d = (steering_frame & (bus5 & bus4 & bus3 & bus2) # (bus5 & !bus4 & bus3) # (!bus5 & !bus4 & !bus3) # (!bus5 & bus4 & (bus3 # bus2))) # (!steering_frame & LSBduty2);
LSBduty1.d = (steering_frame & (bus5 & bus4 & bus3 & !bus2) #

```

```

(bus5 & !bus4 & bus2) # (!bus5 & bus4 & bus3 & !bus2) # (!bus5 & !bus3 & (bus4 # bus2))) # (!steering_frame & LSBduty1);

LSBduty0.d = (steering_frame & (bus1)) # (!steering_frame & LSBduty0);

Steering Generator.pld

Name sterpw90;
Partno GAL22V10;
Date 05/27/02;
Revision XX;
Designer XXXXX;
Company XXXXX;
Assembly XXXXX;
Location XXXXX;
Device g22v10;

/*****
/*
/* WINDOW/UNKNOWN */
*****/

/** Inputs **/

Pin 1 = clk;
Pin 2 = reset;

Pin [3..6] = [MSB3..MSB0];
Pin [7..10] = [LSB3..LSB0];
Pin [13..16] = [clkMSB0..clkMSB3];
Pin [20..23] = [clkLSB0..clkLSB3];

/** Outputs **/

Pin 18 = !a0; /* this is the PWM output to the servos */
Pin 19 = temp;

FIELD pwm = [a0];

/** Declarations and Intermediate Variable Definitions **/

a0.ar = reset;
a0.sp = 'b'0;
a0.oe = !reset;

temp = (LSB0 $ clkLSB0) # (LSB1 $ clkLSB1) # (LSB2 $ clkLSB2) # (LSB3 $ clkLSB3) # (MSB0 $ clkMSB0);

sequence pwm
{
    present 'b'0
    default
    next 'b'0;
    if(! ( temp # (MSB1 $ clkMSB1) # (MSB2 $ clkMSB2) # (MSB3 $ clkMSB3) ))
    next 'b'1;
    present 'b'1
    default
    next 'b'1;
    if(!clkLSB0 & !clkLSB1 & !clkLSB2 & !clkLSB3 & !clkMSB0 & !clkMSB1 & !clkMSB2 & !clkMSB3)
    next 'b'0;
}

PIC CODE

#define MAXGEAR 3

```

```

#define IDLE 16

char TRISC@0x87;
char TRISD@0x88;
char TRISE@0x89;
char PORTC@0x07; // Button inputs from steering wheel
char PORTD@0x08; // Gear output display and PIC output enable
Tristate
char PORTE@0x09; // Enable signals to 512kx8 memory
char ADCON0@0x1f;
char ADCON1@0x9f;
char ADRESH@0x1e;

int AdcWheel,AdcGas,AdcBrake;
char AdcWheelState,AdcGasState,AdcBrakeState,AdcSpeedState;
char CurrentGear,GearUp,GearDn;
char CurrentButtons,ButtonChange;
char MemWrite,MemRead,MemLast;

fAdc(char Channel);
void fGear(char Current);
void fButtons(void);
fOut(char Data, char State);
fStrobe(void);
bit_set(char Data, char Index);

main()
{
    TRISB = 0x00; //Set PORTB to all output
    PORTB = 0x00;
    TRISD = 0x00; //Set PORTD to all output
    PORTD = 0x03; //b00000011
    TRISE = 0x00; //Set PORTE to all output
    PORTE = 0x05; //b00000101
    TRISA = 0xff; //Set PORTA to all input
    TRISC = 0xff; //Set PORTC to all input

    ADCON0 = 0x81; //Configure and turn on A/D Module
    ADCON1 = 0x02; //Set PORTA to analog and RIGHT justify result
    //with PORTE on I/O

    CurrentGear = 1;
    GearUp = 0;
    GearDn = 0;
    MemRead = 0;
    MemWrite = 0;
    MemLast = 0;
    ButtonChange = 0;
    CurrentButtons = 0;

    int iter;

    delay_ms(2);

    while(1)
    {
        iter = 0;

        for(iter;iter<3;iter++)
        {
            fGear(PORTC);

            if(iter == 0)
            {
                AdcGasState = fAdc(1);
                AdcBrakeState = fAdc(2);

                if((AdcBrakeState < IDLE) && (CurrentGear > 0))
                {
                    AdcSpeedState = IDLE;
                    CurrentGear = 1;
                }
                else if((AdcGasState > IDLE) && (AdcBrakeState == IDLE) &&
                    (CurrentGear > 0))
                {
                    AdcSpeedState = AdcGasState;
                    else if((AdcBrakeState < IDLE) && (CurrentGear == 0))
                    {
                        AdcSpeedState = AdcBrakeState;
                    }
                    else
                    {
                        AdcSpeedState = IDLE;
                    }
                    PORTB = fOut(AdcSpeedState,iter);
                }
            }
            else if(iter == 1)
            {
                AdcWheelState = fAdc(0);
                PORTB = fOut(AdcWheelState,iter);
            }
            else
            {
                fButtons();
                PORTB = fOut(CurrentButtons,iter);
                if(MemLast == 1) // Send one last data frame
                {
                    set_bit(PORTE,1); // a flag to determine end of data
                }
                else
                {
                    clear_bit(PORTE,1);
                }
            }
            if((MemWrite == 1) || (MemLast == 1) || (MemRead == 1))
            {
                clear_bit(PORTD,1); // Send a Clock pulse to the
                set_bit(PORTD,1); // for a new address
                clear_bit(PORTD,0); // Count Addresses on
            }
            else
            {
                set_bit(PORTD,0); // Reset Address on 74LS93s
            }
            for new // sequence
            {
                delay_ms(50); // Shortest amount of delay
            }
            for RF // Transmission
            {
                if((MemWrite == 1) || (MemLast == 1))
                {
                    clear_bit(PORTE,0); // Send a Write enable signal to
                    set_bit(PORTE,0); // the 512kx8
                }
                fStrobe(); // Data is valid, send to car
            }
        }
    }

fAdc(char Channel)
{
    char Adc0 = 0;
    char Adc1 = 0;
    char Adc2 = 0;

    switch(Channel) //Select which ADC channel
    {
        case 0:
            ADCON0 = 0x81; //ADC 1 Enable AtoD
            break;
        case 1:
            ADCON0 = 0x89; //ADC 2 Enable AtoD
            break;
        case 2:
            ADCON0 = 0x91; //ADC 3 Enable AtoD
            break;
        default:
            break;
    }
}

```

```

        ADCON0 = 0x81;    //ADC 1 Enable AtoD
        break;
    }

    delay_us(100);

    set_bit(ADCON0,2);

    while(bit_set(ADCON0,2) == 1);

    switch(Channel)
    {
        case 0:    // Calculate ADC for Wheel position

            Adc0 = ADRESH;

            if(Adc0 >= 96)
                return 31;
            else if((Adc0 >= 68) && (Adc0 < 96))
                return ((Adc0 - 34)/2);
            else if((Adc0 >= 60) && (Adc0 < 68))
                return IDLE;
            else if((Adc0 >= 12) && (Adc0 < 60))
                return ((Adc0 - 12)/3);
            else if(Adc0 < 12)
                return 0;
            else
                return IDLE;
            break;

        case 1:    // Calculate ADC for Gas pedal position

            Adc1 = ADRESH;

            if(CurrentGear > 0)
            {
                if((Adc1 >= 220) && (CurrentGear <= 1)) // Max 224
                    return (IDLE + (4 * (CurrentGear - 1)));
                else if((Adc1 >= 220) && (CurrentGear > 1))
                    return (17 + (4 * (CurrentGear - 1)));
                else if((Adc1 >= 208) && (Adc1 < 220))
                    return (18 + (4 * (CurrentGear - 1)));
                else if((Adc1 >= 195) && (Adc1 < 208))
                    return (19 + (4 * (CurrentGear - 1)));
                else
                    return (20 + (4 * (CurrentGear - 1)));
            }
            else
                return IDLE;
            break;

        case 2:    // Calculate ADC for Brake pedal position

            Adc2 = ADRESH;

            if(Adc2 < 110)    // Up 80 Dn 200
                return IDLE;
            else if((Adc2 >= 110) && (Adc2 < 155))
                return 6;
            else if((Adc2 >= 155) && (Adc2 < 175))
                return 5;
            else if(Adc2 >= 175)
                return 4;
            else
                return IDLE;
            break;

        default:

            return IDLE;
            break;
    }
}

void fGear(char Current)    // Calculates which gear the car should be
{
    // in according to paddle pushes

    if(((bit_set(Current,4) != 1) && (CurrentGear < MAXGEAR)) && (GearUp == 0))

```

```

    {
        CurrentGear = CurrentGear + 1;
        GearUp = 1;
    }
    else if((bit_set(Current,4) == 1) && (GearUp == 1))
        GearUp = 0;

    if(((bit_set(Current,5) != 1) && (CurrentGear > 0)) && (GearDn == 0))
    {
        CurrentGear = CurrentGear - 1;
        GearDn = 1;
    }
    else if((bit_set(Current,5) == 1) && (GearDn == 1))
        GearDn = 0;

    if(CurrentGear == 0)    //Use upper 4 bits of PORTD
    {
        set_bit(PORTD,7);    // 1100XXXXb Output a 12 for Reverse
        set_bit(PORTD,6);
        clear_bit(PORTD,5);
        clear_bit(PORTD,4);
    }
    else if(CurrentGear == 1)
    {
        clear_bit(PORTD,7);    // 0001XXXXb Output a 1 for 1st
        clear_bit(PORTD,6);
        clear_bit(PORTD,5);
        set_bit(PORTD,4);
    }
    else if(CurrentGear == 2)
    {
        clear_bit(PORTD,7);    // 0010XXXXb Output a 2 for 2nd
        clear_bit(PORTD,6);
        set_bit(PORTD,5);
        clear_bit(PORTD,4);
    }
    else if(CurrentGear == 3)
    {
        clear_bit(PORTD,7);    // 0011XXXXb Output a 3 for 3rd
        clear_bit(PORTD,6);
        set_bit(PORTD,5);
        set_bit(PORTD,4);
    }
    else
    {
        clear_bit(PORTD,7);    // 0001XXXXb Output a 1 for 1st
        clear_bit(PORTD,6);
        clear_bit(PORTD,5);
        set_bit(PORTD,4);
    }
}

void fButtons(void)
{
    CurrentButtons = ~PORTC;
    clear_bit(CurrentButtons,4);

    MemLast = 0;

    if(MemRead == 0)    // WRITE TO MEMORY
    {
        if((bit_set(CurrentButtons,2) == 1) && (ButtonChange == 0))
        {
            ButtonChange = 1;
            MemWrite = 1;
            set_bit(PORTD,3);
        }
        else if((bit_set(CurrentButtons,2) == 0) && (ButtonChange == 1))
            ButtonChange = 2;
        else if((bit_set(CurrentButtons,2) == 1) && (ButtonChange == 2))
            ButtonChange = 3;
        else if((bit_set(CurrentButtons,2) == 0) && (ButtonChange == 3))
        {
            ButtonChange = 0;
            MemLast = 1;
            MemWrite = 0;
            clear_bit(PORTD,3);
        }
    }
}

```

```

if((MemWrite == 0) && (MemLast == 0)) // READ FROM MEMORY
{
    if((bit_set(CurrentButtons,3) == 1) && (ButtonChange == 0))
    {
        set_bit(PORTD,2);    // Disable PIC data output
        delay_us(25);
        ButtonChange = 1;
        MemRead = 1;
        clear_bit(PORTE,2);    // Enable Mem data output
    }
    else if((bit_set(CurrentButtons,3) == 0) && (ButtonChange == 1))
        ButtonChange = 2;
    else if((bit_set(CurrentButtons,3) == 1) && (ButtonChange == 2))
        ButtonChange = 3;
    else if((bit_set(CurrentButtons,3) == 0) && (ButtonChange == 3))
    {
        set_bit(PORTE,2);    // Disable Mem data output
        delay_us(25);
        ButtonChange = 0;
        MemRead = 0;
        clear_bit(PORTD,2);    // Enable PIC data output
    }

    if((MemRead == 1) && (bit_set(CurrentButtons,7) == 0))
    {
        ButtonChange = 3;    // Reached end of memory
        set_bit(PORTE,2);    // return to User control
    }
}

fOut(char Data, char State)    //Formats the Data char to be ready
{
    //for output by placing an address
    char tempData = Data << 1; //at the MSB and shifting left 1 to
    clear_bit(tempData,0);    //make room for a parity bit

    switch(State)
    {
        case 0:
            clear_bit(tempData,7);
            clear_bit(tempData,6);
            return tempData;
            break;

        case 1:
            clear_bit(tempData,7);
            set_bit(tempData,6);
            return tempData;
            break;

        case 2:
            set_bit(tempData,7);
            clear_bit(tempData,6);
            return tempData;
            break;
    }
}

fStrobe(void)
{
    set_bit(PORTB,0);
    clear_bit(PORTB,0);
}

bit_set(char Data, char Bit) //Checks to see if the selected
{
    //bit in a char is high or low
    switch(Bit)
    {
        case 0:

            if((Data % 2) == 1)
                return 1;
            else
                return 0;
            break;

        case 1:

            if(((Data % 4) / 2) == 1)

```



```

    }
}

package metaswarm.node.components.icon {
    import flash.display.*;

    public class IconButton extends SimpleButton{

        private static const BLACK:uint = 0x231F20;
        private static const WHITE:uint = 0xFFFFFFFF;
        private static const BRIGHTRED:uint = 0xFF3333;
        private static const BRIGHTBLUE:uint = 0x66CDEF;

        public var size:uint;
        public var type:String;

        public function IconButton() {
            this.size = 3;
            this.type = "icon";
            downState = new IconButtonState(BRIGHTBLUE,
BLACK, size);
            overState = new IconButtonState(BRIGHTRED,
BLACK, size);
            upState = new IconButtonState(WHITE,
BLACK, size);
            hitTestState = new IconButtonState(WHITE,
BLACK, size);
            hitTestState.x = -(size / 4);
            hitTestState.y = hitTestState.x;
            useHandCursor = true;
        }

        public function forceOver():void{
            upState = overState;
        }

        public function restoreOver():void{
            upState = hitTestState;
        }

        /*//should be draw()
        public function make():void {
            icon.graphics.beginFill(0x0000ff);
            icon.graphics.lineStyle(0);
            icon.graphics.drawRect(0, 0, 10, 10);
            icon.graphics.endFill();
        }
        */

    }
}

package metaswarm.node.components.icon {
    import flash.display.*;
    import flash.text.*;

    /*//should this extend shape instead????
    public class IconButtonState extends Sprite {
        //private var typeOfButton:uint;
        private var bgColor:uint;
        private var lineColor:uint;
        private var size:uint;

        public function IconButtonState(lineColor:uint,
bgColor:uint, size:uint) {
            //this.typeOfButton = typeOfButton;
            this.bgColor = bgColor;
            this.lineColor = lineColor;
            this.size = size;
            draw();
        }

        private function draw():void {
            //trace("draw the icon button state");
            graphics.beginFill(bgColor);
            graphics.lineStyle(0, lineColor);
            //graphics.drawRect(0, 0, size, size);
            graphics.drawRect(-size, -size, size*2, size*2);
            graphics.endFill();
        }
    }
}

package metaswarm.node.components.icon {
    import flash.display.DisplayObject;
    import flash.display.Graphics;
    import flash.display.Shape;
    import flash.display.Sprite;

    public class IconMaker extends Sprite{
        public var icon:Icon;

        public function IconMaker(icon:Icon):void{
            this.icon = icon;
            init();
        }

        public function init():void {
            //
        }

        public function make():void {
            //trace("make the icon button");
            icon.iconButton = new IconButton();
            icon.addChild(icon.iconButton);
        }
    }
}

package metaswarm.node.components.tag {
    import flash.display.*;
    import flash.text.*;
    import metaswarm.node.components.Particle;

    public class Tag extends Particle{

        //add formatting constants here
        public var tagMaker:TagMaker;
        public var tagButton:TagButton;
        //zoom velocity
        //private var val:String;
        public var t:TextField;
        //var fmt:TextFormat;
        public var uniqArr:Array = new Array();
        public var isUniq:Boolean = new Boolean();

        //need an idea for select and filter functions
        //e.g. select matching text with id eq to this.
        //this is id of array element no textBox
        public var id:uint;

        //cnt not nec, can just use array length
        //var cnt:uint;
        public var dat:Array;
        //var dat:Array = ["cherry", "orange", "soda", "pop"];

        public function Tag():void
        {
            t = new TextField();
            tagMaker = new TagMaker(this);
            //fmt = new TextFormat( );
            init();
        }

        public function init():void {
            visible = false;
            //focusRect = false;
            //tabEnabled = false;
            //tag.mouseEnabled = false;
        }

        public function load(dat:Array):void{
            this.dat = dat;
        }

        public function make():void{
            tagMaker.make();
        }

        public function incr():void{
            if(id < dat.length-1){
                id++;
            }else{
                id=0;
            }
            t.text = dat[id];
            isUniq = uniqArr[id];
            //t.text = String(this.tgx) + ", " +
String(this.tgy);
        }

        public function decr():void{
            if(id > 0){
                id--;
            }else{
                id=dat.length-1;
            }
            t.text = dat[id];
            isUniq = uniqArr[id];
            //t.text = String(this.tgx) + ", " +

```

```

String(this.tgy);
        }

        /*public function getDatAt(id):void{
            return dat[id];
        }
        */

    } //end class
} //end pkg

package metaswarm.node.components.tag {
    import flash.display.*;

    public class TagButton extends SimpleButton{

        private static const BLACK:uint = 0x231F20;
        private static const WHITE:uint = 0xFFFFFFFF;
        private static const BRIGHTRED:uint = 0xFF3333;
        private static const BRIGHTBLUE:uint = 0x66CDEF;

        public var size:uint;
        public var type:String;

        public function TagButton() {
            this.size = 5;
            this.type = "tag";
            downState = new TagButtonState(BRIGHTBLUE,
BLACK, size);
            overState = new TagButtonState(BRIGHTRED,
BLACK, size);
            upState = new TagButtonState(WHITE,
BLACK, size);
            hitTestState = new TagButtonState(WHITE,
BLACK, size);
            hitTestState.x = -(size / 4);
            hitTestState.y = hitTestState.x;
            useHandCursor = true;
        }

        public function forceOver():void{
            upState = overState;
        }

        public function restoreOver():void{
            upState = hitTestState;
        }

        /*//should be draw()
        public function make():void {
            icon.graphics.beginFill(0x0000ff);
            icon.graphics.lineStyle(0);
            icon.graphics.drawRect(0, 0, 10, 10);
            icon.graphics.endFill();
        }
        */

    }
}

package metaswarm.node.components.tag {
    import flash.display.*;
    import flash.text.*;

    public class TagMaker extends Sprite{

        private var tag:Tag;

        public function TagMaker(tag:Tag):void{
            this.tag = tag;
            init();
        }

        public function init():void {
            //
        }

        /*public function make():void {
            //trace("make the tag button");
            tag.tagButton = new TagButton();
            tag.addChild(tag.tagButton);
        }
        */

        public function make():void {
            //tag.tagButton = new TagButton();
            //tag.addChild(tag.tagButton);

            var fmt:TextFormat = new TextFormat( );

            fmt.font = "Arial";
            fmt.size = 5;
            //tag.t.embedFonts = true;
            //tag.t.antiAliasType = AntiAliasType.ADVANCED;
            tag.t.text = "";
            tag.t.setTextFormat(fmt);
            tag.t.selectable = false;
            tag.t.mouseEnabled = false;
            tag.id = 0;

            tag.t.x += 5;
            tag.t.y -= 25;
            //t.width =
            //t.height =
            tag.t.background = true
            tag.t.backgroundColor = 0xCCCCCC; //light gray
            tag.t.border = true;
            tag.t.borderColor = 0x333333; //dark gray
            tag.t.autoSize = TextFieldAutoSize.LEFT;
            //addChild(this);

            tag.t.text = tag.dat[tag.id];

            tag.addChild(tag.t);
        }
    }
}

package metaswarm.node.components.thumb {
    import flash.display.*;
    import flash.text.*;
    import flash.events.*
    import flash.net.*;
    import flash.geom.Matrix;

```



```

//thumb.header.alpha = 50;
//thumb.header.border = true;
//thumb.header.borderColor = 0x000000;

thumb.header.autoSize = TextFieldAutoSize.LEFT;
//addChild(this);*/
thumb.header.text = "123.jpg";

thumb.header.setTextFormat(fmt);

thumb.header.selectable = false;
thumb.header.mouseEnabled = false;
//this.id = 0;
thumb.addChild(thumb.header);
//initTag();
}

private function makeFooter():void {
    var fmt:TextFormat = new TextFormat("Technic",
10, 0x000000);

    thumb.footer.height = 15;
    thumb.footer.width = 125;
    thumb.footer.background = true;
    thumb.footer.backgroundColor = 0xffffffff;

    //thumb.header.autoSize = TextFieldAutoSize.
LEFT;

    thumb.footer.text = "footer";

    thumb.footer.setTextFormat(fmt);

    thumb.footer.selectable = false;
    thumb.footer.mouseEnabled = false;
    //this.id = 0;

    //thumb.footer.x = 0;
    thumb.footer.y = thumb.footer.width;

    thumb.addChild(thumb.footer);
    //initTag();
}

private function makeButtons():void {
    //this should be in thumb
class*****
    thumb.closeButton = new ThumbButton(CLOSETHUMB);
    thumb.popoutButton = new ThumbButton(POPOUT);
    thumb.popinButton = new ThumbButton(POPIN);
    //thumb.loadExtButton:CustomSimpleButton = new
CustomSimpleButton("e");

    var buttonSize:uint = thumb.closeButton.size;
    var thumbWidth:uint = 200;

    //var myButton:Button = new Button();
    //thumb.close.label = "x";
    //thumb.close.emphasized = true;
    //thumb.close.width = 15;
    //close.move(20, 20);

    /*thumb.closeButton.make();
    thumb.popoutButton.make();
    thumb.popinButton.make();
    thumb.loadExtButton.make();*/

    thumb.closeButton.x = thumbWidth - buttonSize;
    //thumb.closeButton.y = thumb.header.height;

    thumb.popoutButton.x = thumbWidth - button-
Size*2;
    //thumb.popoutButton.y = (thumb.header.height +
thumb.bmp.height) - 15;
    //thumb.popoutButton.y = buttonSize;

    thumb.popinButton.x = thumbWidth - buttonSize*3;
    //thumb.popinButton.y = (thumb.header.height +
thumb.bmp.height) - 15;
    //thumb.popinButton.y = buttonSize*2;

    //thumb.loadExtButton.x = thumb.header.width-(15
* 3);
    //thumb.loadExtButton.y = thumb.header.
height-15;

```

```

thumb.addChild(thumb.bmpButton);

thumb.addChild(thumb.closeButton);
thumb.addChild(thumb.popoutButton);
thumb.addChild(thumb.popinButton);
//thumb.addChild(thumb.loadExtButton);
}

package metaswarm.node.nodestates {
    import metaswarm.node.NodeState;

    public class DraggingState implements NodeState{
        private var node:Node;

        public function DraggingState(node:Node)
        {
            //trace("construct DraggingState");
            this.node = node;
        }

        public function select():void{}

        public function deSelect():void{}

        public function toggleSelect():void{}

        public function drag():void{}

        public function drop():void{
            //trace("PickedState drag: goto dragging
state");
            node.icon.visible = false;

            node.icon.stopDrag();
            node.thumb.stopDrag();

            node.thumb.x = node.icon.x;
            node.thumb.y = node.icon.y;
            node.thumb.setTarget(node.icon.x, node.icon.y);
            node.thumb.visible = true;

            //goto dropped state
            node.nodeState = node.dropped;
        }

        //public function dropThumb():void{}

        public function popout():void{}

        public function popin():void{}

        public function close():void{}

        public function setTarget(tgx:Number,
tgy:Number):void{
            //trace("DraggingState switch");
            //node.dot.setTarget(tgx, tgy);
        }

        public function rePosition():void{
            //trace("DraggingState rePosition");
            //node.dot.goToTarget();
            //node.thumb.x = node.icon.x;
            //node.thumb.y = node.icon.y;

            //dragging icon so snap dot to icon
            /*node.dot.x = node.dataBox.x;
            node.dot.y = node.dataBox.y;*/
        }

        public function reSize():void{
            //trace("DraggingState reSize");
            node.icon.scaleToTarget(); //???
        }

        public function startFocus():void{}

        public function stopFocus():void{}
    }
}

```

```

public function startHover():void{}

public function stopHover():void{}
}

package metaswarm.node.nodestates {
    import metaswarm.node.NodeState;

    public class DroppedState implements NodeState{
        private var node:Node;

        public function DroppedState(node:Node)
        {
            //trace("construct DroppedState");
            this.node = node;
        }

        public function select():void{}
        public function deSelect():void{}
        public function toggleSelect():void{}

        public function drag():void{
            //trace("DroppedState drag: goto dragging
state");
            //start dragging
            node.thumb.startDrag();

            //goto to dragging state
            node.nodeState = node.tdragging;
            node.prevState = node.dropped;
        }

        public function drop():void{}

        //public function dropThumb():void{}

        public function popout():void{
            //trace("DroppedState popout");

            //position dataBox next to thumb and show
            //node.dataBox.x = node.thumb.x + node.thumb.
width;

            node.dataBox.x = node.thumb.x + 125;
            node.dataBox.y = node.thumb.y;
            node.dataBox.visible = true;

            //goto popped state
            node.nodeState = node.popped;
        }

        public function popin():void{}

        public function close():void{
            //trace("DroppedState close");

            //position dot at target
            node.dot.snapToTarget();

            //position icon at thumb position
            node.icon.x = node.thumb.x;
            node.icon.y = node.thumb.y;
            node.icon.setTarget(node.dot.x, node.dot.y);
            node.icon.visible = true;

            //hide thumb, but should i dispose of bitmap???
            node.thumb.visible = false;

            //go back to idle
            node.nodeState = node.picked;
        }

        public function setTarget(tgx:Number,
tgy:Number):void{
            //trace("DroppedState switch");

            //preview mainstate needs this to tile
            //node.thumb.setTarget(tgx, tgy);

            //set dot target incase thumb is closed,
            //dot it will get back in place in swarm
            node.dot.setTarget(tgx, tgy);
        }
    }
}

```

```

public function rePosition():void{
    //trace("DroppedState rePosition");

    //preview mainstate need this to tile
    node.thumb.goToTarget();
}

public function startFocus():void{}
public function stopFocus():void{}
public function reSize():void{} //icon is not visible
so don't bother
public function startHover():void{} //change these
names to hover or smth
public function stopHover():void{}
}

package metaswarm.node.nodestates {
    import flash.geom.ColorTransform;
    import metaswarm.node.NodeState;

    public class IdleState implements NodeState{
        private var redTransform:ColorTransform;
        private var blkTransform:ColorTransform;

        private var node:Node;

        function IdleState(node:Node)
        {
            //trace("construct IdleState");
            this.node = node;

            redTransform = new ColorTransform( );
            redTransform.color = 0xFF0000;
            blkTransform = new ColorTransform( );
            blkTransform.color = 0xCCCCCC;
        }

        public function select():void{
            //trace("IdleState select:goto picked state");

            //node.dot.mouseEnabled = false;
            //stopFocus();

            node.dot.visible = false;

            //position icon at dot and make visible
            node.icon.x = node.dot.x;
            node.icon.y = node.dot.y;
            node.icon.setTargetWidth(6);
            node.icon.setTarget(node.dot.x, node.dot.y);
            node.icon.visible = true;

            //position tag at dot and make visible
            node.tag.x = node.dot.x;
            node.tag.y = node.dot.y;
            //node.tag.visible = true;

            //goto picked state
            node.nodeState = node.picked;
        }

        public function deSelect():void{}

        public function toggleSelect():void{
            select();
        }

        //public function filter():void{}

        public function drag():void{}

        public function drop():void{}

        //public function dropThumb():void{}

        public function popout():void{}

        public function popin():void{}

        public function close():void{}

        public function setTarget(tgx:Number,
tgy:Number):void{

```



```

word.
// In this example, just output the values.
for ( var i:int = 0; i < lines.length; i++ ) {
    words = lines[i].split("\t");
    parsedData.push(words);
    //trace(parsedData[i][1]);
}
//gnurbwurk.parsedData = parsedData;
//gnurbwurk.preloadComplete(parsedData);
gnurbwurk.load(parsedData);
//gnurbwurk.main.makePatterns();
}

} //end class
} //end pkg
package metaswarm.subset {
import flash.display.DisplayObject;
import flash.display.Sprite;
import flash.display.Graphics;
import flash.display.Shape;

public class Subset extends Sprite{

public var nodes:Array;
public var tiler:SubsetTiler;
//var count:uint;

//constructor:
public function Subset() {
    nodes = new Array();
    tiler = new SubsetTiler(this);
}

public function tile():void {
    //trace("tile");
    tiler.grid();
}

public function restore():void {
    //trace("tile");
    tiler.restore();
}

public function disable():void {
    trace("disable");
    for (var i:uint=0; i<nodes.length; i++){
        nodes[i].visible = false;
    }
}

} //end class
} //end pkg
package metaswarm.subset {
import flash.display.DisplayObject;
import flash.display.Sprite;
import flash.display.Graphics;
import flash.display.Shape;

public class SubsetTiler extends Sprite{

public var subset:Subset;
//var tileSize:uint;

//constructor:
public function SubsetTiler(subset:Subset){
    this.subset = subset;
    //this.tileSize = 100; //later define dynamically
}

//this is beastly for now. it sets target of both
//and tag, regardless of whether dropped or picked
//and s should not be hard coded!!
public function grid():void{
    //trace("tiler.grid");
    var s:uint = 200;
    var cnt:uint = subset.nodes.length;
    //trace("cnt: " + cnt);
    //var xMargin:uint = s/4;
    //var yMargin:uint = s/4;
    var xsp:uint = s;
    var ysp:uint = s;
    var cols:uint = Math.ceil(((s+ysp) * cnt) /
1080);

    //trace("cols: " + cols);

```

```

var xoff:uint = s/4;
var yoff:uint = s/4;

for (var i:uint=0; i<cnt; i++){
    //trace("subset.nodes[i].thumb.x: " +
subset.nodes[i].meta.x);
    //trace("subset.nodes[i].thumb.y: " +
subset.nodes[i].meta.y);
    var px:Number = subset.nodes[i].thumb.x;
    var py:Number = subset.nodes[i].thumb.y;
    subset.nodes[i].thumb.setPrev(px, py);
    //
    var tgx:Number = xoff + xsp*(i%cols);
    var tgy:Number = yoff + ysp*Math.floor(i/
cols);
    subset.nodes[i].popin();
    subset.nodes[i].thumb.setTarget(tgx,
tgy);
    //subset.nodes[i].tag.setTarget(tgx,
tgy);
}

}

public function restore():void{
    //trace("tiler.restore");
    var cnt:uint = subset.nodes.length;
    for (var i:uint=0; i<cnt; i++){
        //trace("subset.nodes[i].thumb.x: " +
subset.nodes[i].meta.x);
        //trace("subset.nodes[i].thumb.y: " +
subset.nodes[i].meta.y);
        var tgx:Number = subset.nodes[i].thumb.
px;
        var tgy:Number = subset.nodes[i].thumb.
py;
        subset.nodes[i].popin();
        subset.nodes[i].thumb.setTarget(tgx,
tgy);
        //subset.nodes[i].tag.setTarget(tgx,
tgy);
    }
}

} //end class
} //end pkg
package metaswarm.swarm {
import flash.display.DisplayObject;
import flash.display.Sprite;
import flash.display.Graphics;
import flash.display.Shape;
import metaswarm.swarm.swarmstates.BrowningState;
import metaswarm.swarm.swarmstates.GridState;
import metaswarm.swarm.swarmstates.LorenzeState;
import metaswarm.swarm.swarmstates.ScatterState;
import metaswarm.swarm.swarmstates.TypeState;
import metaswarm.swarm.swarmstates.MapState;
import metaswarm.subset.Subset;

public class Swarm extends Sprite{

//omit constants for now

//Except for TextField and Video objects,
//a display object with no content has a
//width of 0, even if you try to set width
//to a different value, so need these
public var w:int;
public var h:int;

//internal composite objects
public var nodes:Array;
public var nodeCnt:uint;
public var propCnt:uint;
public var sortOrder:uint;

//internal states
public var lorenze:SwarmState;
public var browning:SwarmState;
public var scatter:SwarmState;
public var grid:SwarmState;
public var type:SwarmState;
public var map:SwarmState;

//internal state holder
public var swarmState:SwarmState;

```

```

//var swarmLoader:SwarmLoader;
//var patternMaker:PatternMaker;

//constructor:
public function Swarm() {

//instantiate composite obj's
nodes = new Array();

lorenze = new LorenzeState(this);
browning = new BrowningState(this);
scatter = new ScatterState(this);
grid = new GridState(this);
type = new TypeState(this);
map = new MapState(this);

init();

private function init():void{
    //set intial state and show unique
    //tags for that state
    swarmState = grid;
    sortOrder = 2;
    showUniqueTags();
}

//these need to be changed
public function preview():void {
    var dropped:Subset = new Subset();
    //var undropped:Subset = new Subset();
    for (var i:uint=0; i<nodeCnt; i++){
        if (nodes[i].isDropped() || nodes[i].
isPopped()){
            dropped.nodes.push(nodes[i]);
        } else {
            //undropped.push(nodes[i]);
            nodes[i].visible = false;
        }
    }
    dropped.tile();
    //undropped.disable();
}

public function explore():void {
    var dropped:Subset = new Subset();
    //var undropped:Subset = new Subset();
    for (var i:uint=0; i<nodeCnt; i++){
        if (nodes[i].isDropped() || nodes[i].
isPopped()){
            dropped.nodes.push(nodes[i]);
        } else {
            //undropped.push(nodes[i]);
            nodes[i].visible = true;
        }
    }
    dropped.restore();
    //undropped.disable();
}

//methods
public function select(node:Node):void {
    clearSelection();
    node.select();
}

public function add(node:Node):void {
    node.select();
}

public function remove(node:Node):void {
    node.deselect();
}

public function toggleSelect(node:Node):void {
    node.toggleSelect();
}

public function clearSelection():void {
    for (var i:uint=0; i<nodeCnt; i++){
        nodes[i].deselect();
    }
}

public function selectBy(t:String):void {
    clearSelection();
    for (var i:uint=0; i<nodeCnt; i++){
        if (nodes[i].tag.t.text == t){
            nodes[i].select();
        }
    }
}

```

```

}

public function addBy(t:String):void {
    for (var i:uint=0; i<nodeCnt; i++){
        if (nodes[i].tag.t.text == t){
            nodes[i].select();
        }
    }
}

public function filterBy(t:String):void {
    for (var i:uint=0; i<nodeCnt; i++){
        if (nodes[i].tag.t.text != t){
            //trace("deselect");
            nodes[i].deselect();
        }
    }
}

public function popin(node:Node):void{
    node.popin();
}

public function popout(node:Node):void{
    node.popout();
}

public function close(node:Node):void{
    node.close();
}

public function drag(node:Node):void{
    node.drag();
}

public function drop(node:Node):void{
    node.drop();
}

public function dropSelected():void{
    for (var i:uint=0; i<nodeCnt; i++){
        if (nodes[i].isPicked()){
            nodes[i].drop();
        }
    }
}

public function startHover(node:Node):void{
    node.startHover();
}

public function stopHover(node:Node):void{
    //trace("swarm.stopHover");
    node.stopHover();
}

public function startFocusBy(t:String):void {
    for (var i:uint=0; i<nodeCnt; i++){
        if (nodes[i].tag.t.text == t){
            nodes[i].startFocus();
        }
    }
}

public function startSelectByFocus(t:String):void {
    for (var i:uint=0; i<nodeCnt; i++){
        if (nodes[i].tag.t.text == t){
            nodes[i].startFocus();
        }
    }
}

public function startFilterByFocus(t:String):void {
    for (var i:uint=0; i<nodeCnt; i++){
        if (nodes[i].tag.t.text == t && nodes[i].
isPicked()){
            nodes[i].startFocus();
        }
    }
}

public function stopFocusBy():void {
    for (var i:uint=0; i<nodeCnt; i++){
        nodes[i].stopFocus();
    }
}

public function printOutNodes():void{
    trace("printOutCoordinates: *****");
    for (var i:uint=0; i<nodeCnt; i++){
        trace("node " + i + ": ");
    }
}

```

```

        for(var j:uint=0; j<propCnt; j++){
            trace("xpos,ypos " + j + ": " +
nodes[i].xpos[0][j] + ", " + nodes[i].ypos[0][j]);
        }
    }

    public function rePosition():void{
        //trace("swarm rePosition");
        for(var i:uint=0; i<nodeCnt; i++){
            nodes[i].rePosition();
        }
    }

    public function reSize():void{
        //trace("swarm reSize");
        for(var i:uint=0; i<nodeCnt; i++){
            nodes[i].reSize();
        }
    }

    public function incrSort():void{
        //trace("incrSort");
        if(sortOrder < propCnt-1){
            sortOrder++;
        }else{
            sortOrder = 0;
        }
        for(var i:uint=0; i<nodeCnt; i++){
            //swarm.nodes[i].tag.setTxt(1);
            nodes[i].tag.incr();
        }
        setPattern();
        showUniqueTags();
    }

    public function decrSort():void{
        //trace("decrSort");
        if(sortOrder > 0){
            sortOrder--;
        }else{
            sortOrder = propCnt-1;
        }
        for(var i:uint=0; i<nodeCnt; i++){
            //swarm.nodes[i].tag.setTxt(1);
            nodes[i].tag.decr();
        }
        setPattern();
        showUniqueTags();
    }

    public function showUniqueTags():void{
        for(var i:uint=0; i<nodeCnt; i++){
            nodes[i].tag.visible = nodes[i].tag.isU-
niq;
        }
    }

    //delegated tas
ks*****
    public function incrState():void{
        //trace("delegate incrState");
        swarmState.incrState();
    }

    public function decrState():void{
        //trace("delegate decrState");
        swarmState.decrState();
    }

    public function setPattern():void{
        //trace("delegate swarm switch");
        swarmState.setPattern();
    }

    //end swarm
} //end pkg

package metaswarm.swarm {
    import flash.display.*;
    import flash.text.*;
    import flash.events.*
    import flash.net.*;
    import metaswarm.node.NodeLoader;
    import metaswarm.*;

    //internal interface methods
    //function incrSort():void;
    //function decrSort():void;
    function incrState():void;
    function decrState():void;
    function setPattern():void;
}

package metaswarm.swarm.patternmaker {
    import flash.display.*;
    import flash.utils.*;
    import flash.events.*;
    import flash.geom.*;
    import flash.text.*;
    import metaswarm.swarm.patterns.GeoMapper;
    import metaswarm.swarm.patterns.LorenzeMaker;
    import metaswarm.swarm.patterns.TypeMaker;
    import metaswarm.swarm.Swarm;
    import metaswarm.swarm.patterns.GridMaker;

    //class needs to be broken up

    public class PatternMaker extends Sprite{
        private var _swarm:Swarm;
        //var typeMaker:TypeMaker; //don't know why i don't lo-
calize to function
    }
}

```

```

public class SwarmLoader extends Sprite {
    private var _swarm:Swarm;

    public function SwarmLoader(swarm:Swarm)
    {
        this._swarm = swarm;
        //this.loadProg = new TextField();

        init();
    }

    private function init():void
    {
        //loadProg.width = stage.stageWidth;
        //loadProg.height = stage.stageHeight;
        //addChild(loadProg);
    }

    public function load(dat:Array):void{
        //trace("swarmloader load");
        _swarm.nodeCnt = dat.length;
        _swarm.propCnt = dat[0].length;
        //create nodes and add each to display list
        for(var i:uint=0; i<_swarm.nodeCnt; i++){
            var tmp:Node = new Node();
            var nodeLoader:NodeLoader = new NodeLoader(tmp);

            nodeLoader.load(dat[i]); //maybe call after push
            _swarm.nodes.push(tmp);
        }
    }

    public function make():void{
        //swarm.patternMaker.make(); //decouple from swarm
        for(var i:uint=0; i<_swarm.nodeCnt; i++){
            var nodeLoader:NodeLoader = new NodeLoader(_
swarm.nodes[i]);
            nodeLoader.make();
        }
    }

    public function go():void{
        //swarm.swarmState = swarm.grid;
        //swarm.sortOrder = 0;
        for(var i:uint=0; i<_swarm.nodeCnt; i++){
            var nodeLoader:NodeLoader = new NodeLoader(_
swarm.nodes[i]);
            nodeLoader.go();
            _swarm.addChild(_swarm.nodes[i]);
        }
        //swarm.setPattern();
    }
} //end class
} //end pkg

package metaswarm.swarm {
    //fsm interface
    public interface SwarmState{
        //internal interface methods
        //function incrSort():void;
        //function decrSort():void;
        function incrState():void;
        function decrState():void;
        function setPattern():void;
    }
}

package metaswarm.swarm.patternmaker {
    import flash.display.*;
    import flash.utils.*;
    import flash.events.*;
    import flash.geom.*;
    import flash.text.*;
    import metaswarm.swarm.patterns.GeoMapper;
    import metaswarm.swarm.patterns.LorenzeMaker;
    import metaswarm.swarm.patterns.TypeMaker;
    import metaswarm.swarm.Swarm;
    import metaswarm.swarm.patterns.GridMaker;

    //class needs to be broken up

    public class PatternMaker extends Sprite{
        private var _swarm:Swarm;
        //var typeMaker:TypeMaker; //don't know why i don't lo-
calize to function
    }
}

```

```

public function PatternMaker(swarm:Swarm):void{
    this._swarm = swarm;
    //this.typeMaker = new TypeMaker();
}

public function make():void
{
    //property count is hardcoded for now so can't
    //add/remove patterns w/out changing
    for(var j:uint=0; j<_swarm.propCnt; j++){
        sortBy(j);
        setUniqueTags(j);
        grid(0, j);
        scatter(1, j);
        browning(2, j);
        lorenze(3, j);
        type(4, j);
        map(5, j);
    }
}

public function setUniqueTags(tid:uint):void{
    var prevTag:String = new String();
    var curTag:String = new String();
    prevTag = "";
    for(var i:uint=0; i<_swarm.nodeCnt; i++){
        curTag = _swarm.nodes[i].dat[tid];
        if(curTag == prevTag){
            _swarm.nodes[i].tag.uniArr[tid]
= false;
        }else{
            _swarm.nodes[i].tag.uniArr[tid]
= true;
        }
        prevTag = _swarm.nodes[i].dat[tid];
    }
}

public function type(pid:uint, sid:uint):void
{
    //trace("PatternMaker->type()");

    //generate coordinates
    var typeMaker:TypeMaker = new TypeMaker();
    var points:Array = typeMaker.make("me+", _
swarm.nodeCnt, _swarm.w);

    //map coordinates to nodes positions
    for(var i:uint=0; i<_swarm.nodeCnt; i++){
        _swarm.nodes[i].xpos[pid][sid] =
points[i][0];
        _swarm.nodes[i].ypos[pid][sid] =
points[i][1];
    }
}

//this is beastly for now
public function grid(pid:uint, sid:uint):void
{
    //generate coordinates
    var gridMaker:GridMaker = new GridMaker();
    var points:Array = gridMaker.make(_swarm.no-
deCnt, _swarm.w, _swarm.h);

    //map coordinates to nodes positions
    for(var i:uint=0; i<_swarm.nodeCnt; i++){
        _swarm.nodes[i].xpos[pid][sid] =
points[i][0];
        _swarm.nodes[i].ypos[pid][sid] =
points[i][1];
    }
}

public function scatter(pid:uint, sid:uint):void
{
    for(var i:uint=0; i<_swarm.nodeCnt; i++){
        _swarm.nodes[i].xpos[pid][sid] = Math.
random()*_swarm.w;
        _swarm.nodes[i].ypos[pid][sid] = Math.
random()*_swarm.h;
    }
}

```

```

//Lorenze Attractor Pattern-just guessed on random
range
public function lorenze(pid:uint, sid:uint):void
{
    //generate coordinates
    var lorenzeMaker:LorenzeMaker = new LorenzeMak-
er();
    var points:Array = lorenzeMaker.make(_swarm.no-
deCnt, _swarm.w, _swarm.h);

    //map coordinates to nodes positions
    for(var i:uint=0; i<_swarm.nodeCnt; i++){
        _swarm.nodes[i].xpos[pid][sid] =
points[i][0];
        _swarm.nodes[i].ypos[pid][sid] =
points[i][1];
    }
}

/**genBrowning
public function browning(pid:uint, sid:uint):void{
    var range:int = 20;
    swarm.nodes[0].xpos[pid][sid] = Math.
random()*swarm.w;
    swarm.nodes[0].ypos[pid][sid] = Math.
random()*swarm.h;
    for(var i:uint=1; i<swarm.nodeCnt; i++){
        if(swarm.nodes[i].tag.dat[sid] == swarm.
nodes[i-1].tag.dat[sid]){
            swarm.nodes[i].xpos[pid][sid] =
swarm.nodes[i-1].xpos[pid][sid] + (Math.random()-0.5)*range;
            swarm.nodes[i].ypos[pid][sid] =
swarm.nodes[i-1].ypos[pid][sid] + (Math.random()-0.5)*range;
        }else{
            swarm.nodes[i].xpos[pid][sid] =
Math.random()*swarm.w;
            swarm.nodes[i].ypos[pid][sid] =
Math.random()*swarm.h;
        }
    }
}

//genBrowning
public function browning(pid:uint, sid:uint):void
{
    var range:int = 25;
    _swarm.nodes[0].xpos[pid][sid] = _swarm.w/2;
    _swarm.nodes[0].ypos[pid][sid] = _swarm.h/2;
    for(var i:uint=1; i<_swarm.nodeCnt; i++){
        _swarm.nodes[i].xpos[pid][sid] = _swarm.
nodes[i-1].xpos[pid][sid] + (Math.random()-0.5)*range;
        _swarm.nodes[i].ypos[pid][sid] = _swarm.
nodes[i-1].ypos[pid][sid] + (Math.random()-0.5)*range;
    }
}

//genBrowning
public function map(pid:uint, sid:uint):void
{
    var geoMapper:GeoMapper = new GeoMapper();

    //var coordinates:Array = new Array();
    var latIndex:Number = 6;
    var longIndex:Number = 5;

    //for each node
    for(var i:uint=1; i<_swarm.nodeCnt; i++){
        var geoPoint:Array = [_swarm.nodes[i].
dat[longIndex], _swarm.nodes[i].dat[latIndex]];
        //coordinates.push(geoPoint);

        //convert node.dat to screen coordinates
        var point:Array = geoMapper.
geoToScreen(geoPoint, _swarm.h/2);

        //assign to node pos
        _swarm.nodes[i].xpos[pid][sid] =
point[0];
        _swarm.nodes[i].ypos[pid][sid] =
point[1];
    }
}

//bubble sort. put in util class later
public function sortBy(tid:uint):void

```